# Part II Process Management Chapter 7: Deadlocks

### **System Model**

System resources are utilized in the following way:

- Request: If a process makes a request to use a system resource which cannot be granted immediately, then the requesting process blocks until it can acquire the resource.
- **\*Use:**The process can operate on the resource.

**Release:** The process releases the resource.

Deadlock: A set of processes is in a deadlock state when every process in the set is waiting for an event that can only be caused by another process in the set.

#### **Deadlock: Necessary Conditions**

- **For a deadlock to occur, each of the following four conditions must hold.** 
  - Mutual Exclusion: At least one resource must be held in a non-sharable way.
  - Hold and Wait: A process must be holding a resource and waiting for another.
  - **No Preemption:** Resource cannot be preempted.
  - Circular Wait: A waits for B, B waits for C, C waits for A.

# **Handling Deadlocks**

- **Deadlock Prevention and Avoidance:** Make sure deadlock will never happen.
  - **\*Prevention:** Ensure one of the four conditions fails.
  - Avoidance: The OS needs more information so that it can determine if the current request can be satisfied or delayed.
- **Deadlock** : Allow a system to enter a deadlock situation, detect it, and recover.
- **Ignore Deadlock:** Pretend deadlocks never occur in the system.

#### Deadlock Prevention: 1/4 Mutual Exclusion

- By ensuring that at least one of the four conditions cannot hold, we can prevent the occurrence of a deadlock.
- Mutual Exclusion: Some sharable resources must be accessed exclusively (*e.g.*, printer), which means we cannot deny the mutual exclusion condition.

# Deadlock Prevention: 2/4 Hold and Wait

- No process can hold some resources and then request for other resources.
- **Two strategies are possible:** 
  - A process must acquire *all* resources before it runs.
  - When a process requests for resources, it must hold none (*i.e.*, returning resources before requesting for more).

**Resource utilization** may be low, since many resources will be held and unused for a long time.

**Starvation** is possible. A process that needs some popular resources my have to wait indefinitely.

#### Deadlock Prevention: 3/4 No Preemption

- **Resources that are being held by the requesting process are preempted. There are two strategies:** 
  - If a process is holding some resources and requesting for some others that are being held by other processes, the resources of the requesting process are preempted. The preempted resources become available.
  - **\*** If the requested resources are not available:
    - If they are being held by processes that are waiting for additional resources, these resources are preempted and given to the requesting process.
    - > Otherwise, the requesting process waits until the requested resources become available. While it is waiting, its resources may be preempted.
    - This works only if the state of the process and resources can be saved and restored easily (e.g., CPU & memory).

### **Deadlock Prevention: 4/4 Circular Waiting**

- **To break the circular waiting condition, we can order all resource types (***e.g.***, tapes, printers).**
- A process can only request resources higher than the resource types it holds.
- Suppose the ordering of tapes, disks, and printers are 1, 4, and 8. If a process holds a disk (4), it can only ask a printer (8) and cannot request a tape (1).
- A process must release some lower order resources to request a lower order resource. To get tapes (1), a process must release its disk (4).
- □ In this way, no deadlock is possible. Why?

#### **Deadlock Avoidance: 1/5**

- Each process provides the maximum number of resources of each type it needs.
- ❑ With these information, there are algorithms that can ensure the system will never enter a deadlock state. This is *deadlock avoidance*.
- □ A sequence of processes  $\langle P_1, P_2, ..., P_n \rangle$  is a *safe sequence* if for each process  $P_i$  in the sequence, its resource requests can be satisfied by the remaining resources and the sum of all resources that are being held by  $P_1, P_2, ..., P_{i-1}$ . This means we can suspend  $P_i$  and run  $P_1, P_2, ..., P_{i-1}$  until they complete. Then,  $P_i$  will have all resources to run.

# **Deadlock Avoidance: 2/5**

- A state is *safe* if the system can allocate resources to each process (up to its maximum, of course) in some order and still avoid a deadlock.
- In other word, a state is *safe* if there is a safe sequence.
   Otherwise, if no safe sequence exists, the system state is *unsafe*.
- An unsafe state is not necessarily a deadlock state.
   On the other hand, a deadlock state is an unsafe state.



### **Deadlock Avoidance: 3/5**

A system has 12 tapes and three processes *A*, *B*, *C*. At time  $t_0$ , we have: 3 free tapes

	Max needs	Current holding			Will need
A	10		5		5
B	4		2		2
С	9		2		7
			$\overline{}$		

**Then,**  $\langle B, A, C \rangle$  is a safe sequence (safe state).

**The system has 12-(5+2+2)=3 free tapes.** 

□ Since *B* needs 2 tapes, it can take 2, run, and return 4. After *B* completes, the system has (3-2)+4=5 tapes. *A* now can take all 5 tapes and run. Finally, *A* returns 10 tapes for *C* to take 7 of them.

#### **Deadlock Avoidance: 4/5**

❑ A system has 12 tapes and three processes A, B, C. At time t<sub>1</sub>, C has one more tape:

	Max needs	Current holding	Will need
A	10	5	5
B	4	2	2
С	9	3	6

- **The system has 12-(5+2+3)=2 free tapes.**
- At this point, only *B* can take these 2 and run. It returns 4, making 4 free tapes available.
- **But, none of** *A* **and** *C* **can run, and a deadlock occurs.**
- **The problem is due to granting** *C* **one more tape.**

# **Deadlock Avoidance: 5/5**

- A *deadlock avoidance algorithm* ensures that the system is always in a safe state. Therefore, no deadlock can occur.
- **Resource requests are granted only if in doing** so the system is still in a safe state.
- Consequently, resource utilization may be *lower* than those systems without using a deadlock avoidance algorithm.

# Banker's Algorithm: 1/2

- **The system has** *m* **resource types and** *n* **processes.**
- **Each process must declare its maximum needs.**
- **The following arrays are used:** 
  - Available[1..m]: one entry for each resource. Available[i]=k means resource type i has k units available.
  - Max[1..n, 1..m]: maximum demand of each process. Max[i,j]=k means process i needs k units of resource j.
  - Allocation[1..n,1..m]: resources allocated to each process. Allocation[i,j]=k means process i is currently allocated k units of resource j.
  - \* Need[1..n,1..m]: the remaining resource need of each process. Need[i,j]=k means process i needs k more units of resource j.

#### **Banker's Algorithm: 2/2**

- □ We will use *A*[*i*,\*] to indicate the *i*-th row of matrix *A*.
- □ Given two arrays A[1..m] and  $B[1..m], A \leq B$  if  $A[i] \leq B[i]$  for all *i*. Given two matrices A[1..n, 1..m]and  $B[1..n, 1..m], A[i,*] \leq B[i,*]$  if  $A[i,j] \leq B[i,j]$  for all *j*.
- □ When a resource request is made by process *i*, this algorithm calls the Resource-Request algorithm to determine if the request can be granted. The Resource-Request algorithm calls the Safety Algorithm to determine if a state is safe.

# **Safety Algorithm**

- 1. Let *Work*[1..*m*] and *Finish*[1..*n*] be two working arrays.
- 2. Work := Available and Finish[i]=FALSE for all i
- **3.** Find an *i* such that both
  - Finish[i] = FALSE // process i is not yet done
  - *Need*[*i*,\*] ≤ Work // its need can be satisfied
    If no such *i* exists, go to Step 5
- 4. Work = Work + Allocation[i,\*] // run it and reclaim Finish[i] = TRUE // process i completes go to Step 3
- 5. If *Finish*[*i*] = *TRUE* for all *i*, the system is in a safe state.

# **Resource-Request Algorithm**

- 1. Let *Request*[1..*n*,1..*m*] be the request matrix. *Request*[*i*,*j*]=*k* means process *i* requests *k* units of resource *j*.
- 2. If *Request*[*i*,\*]≤*Need*[*i*,\*], go to Step 3. Otherwise, it is an error.
- 3. If *Request*[*i*,\*]≤*Available*, go to Step 4. Otherwise, process *i* waits.
- 4. Do the following:

Available = Available – Request[i,\*]

Allocation[i,\*] = Allocation[i,\*]+Request[i,\*]

Need[i,\*] = Need[i,\*] – Request[i,\*]

If the result is a safe state (Safety Algorithm), the request is granted. Otherwise, process *i* waits and the

resource-allocation tables are restored back to the original.

#### Example: 1/4

□ Consider a system of 5 processes *A*, *B*, *C*, *D* and *E*, and 3 resource types (*X*=10, *Y*=5, *Z*=7). At time *t*<sub>0</sub>, we have

	All	ocati	on		Max	Λ	Need=Max-Alloc				Available		
	X Y Z			X	Y	Ζ	X	Y	Ζ	X	Y	Ζ	
A	0	1	0	7	5	3	7	4	3	3	3	2	
B	2	0	0	3	2	2	1	2	2				
С	3	0	2	9	0	2	6	0	0				
D	2	1	1	2	2	2	0	1	1				
E	0	0	2	4	3	3	4	3	1				

- A safe sequence is <*B*,*D*,*E*,*C*,*A*>. Since *B*'s [1,2,2]≤ *Avail*'s [3,3,2], *B* runs. Then, *Avail*=[2,0,0]+[3,3,2]=[5,3,2]. *D* runs next. After this, *Avail*=[5,3,2]+[2,1,1]=[7,4,3]. *E* runs next.
- □ *Avail*=[7,4,3]+[0,0,2]=[7,4,5]. Since *C*'s [6,0,0]≤*Avail*=[7,4,5], *C* runs. After this, *Avail*=[7,4,5]+[3,0,2]=[10,4,7] and *A* runs.

□ There are other safe sequences:  $\langle D, E, B, A, C \rangle$ ,  $\langle D, B, A, E, C_1 \rangle$ , ...

#### Example: 2/4

- Now suppose process *B* asks for 1 *X* and 2 Zs. More precisely, *Request<sub>B</sub>* = [1,0,2]. *Is the system still in a safe state if this request is granted?*
- □ Since  $Request_B = [1,0,2] \le Available = [3,3,2]$ , this request may be granted as long as the system is safe.
- □ If this request is actually granted, we have the following:



### Example: 3/4

	All	ocati	on		Max Need=Max-Alloc					Available		
	X	Y	Ζ	X	Y	Ζ	X	Y	Ζ	X	Y	Ζ
A	0	1	0	7	5	3	7	4	3	2	3	0
B	3	0	2	3	2	2	0	2	0		******	*****
С	3	0	2	9	0	2	6	0	0			
D	2	1	1	2	2	2	0	1	1			
E	0	0	2	4	3	3	4	3	1			

□ Is the system in a safe state after this allocation?

- □ Yes, because the safety algorithm will provide a safe sequence <*B*,*D*,*E*,*A*,*C*>. Verify it by yourself.
- □ Therefore, *B*'s request of [1,0,2] can safely be made.

#### Example: 4/4

	All	ocati	on		Max Need=Max-Alloc					Available		
	X	Y	Ζ	X	Y	Ζ	X	Y	Ζ	X	Y	Ζ
A	0	1	0	7	5	3	7	4	3	2	3	0
B	3	0	2	3	2	2	0	2	0			
С	3	0	2	9	0	2	6	0	0			
D	2	1	1	2	2	2	0	1	1			
E	0	0	2	4	3	3	4	3	1			

- □ After this allocation, *E*'s request  $Request_E = [3,3,0]$ cannot be granted since  $Request_E = [3,3,0] \le [2,3,0]$  is false.
- □ *A*'s request  $\frac{Request_A}{Request_A} = [0,2,0]$  cannot be granted because the system will be unsafe.
- □ If  $Request_A = [0,2,0]$  is granted, Available = [2,1,0].
- □ None of the five processes can finish and the system is unsafe.

#### **Deadlock Detection**

- If a system does not use a deadlock prevention or a deadlock avoidance algorithm, then a deadlock situation may occur. Thus, we need
  - An algorithm that can examine the system state to determine if a deadlock has occurred. This is a *deadlock detection* algorithm.
  - An algorithm that can help recover from a deadlock. This is a *recovery* algorithm.
- A deadlock detection algorithm does not have to know the maximum need Max and the current need Need. It uses only Available, Allocation and Request.

### **Deadlock Detection Algorithm**

- **1.** Let *Work*[1..*m*] and *Finish*[1..*n*] be two working arrays.
- 2. Work := Available and Finish[i]=FALSE for all i
- **3.** Find an *i* such that both
  - *Finish[i] = FALSE* // process *i* is not yet done
    *Request[i,\*] ≤ Work* // its request can be satisfied
    If no such *i* exists, go to Step 5
- 4. Work = Work + Allocation[i,\*] // run it and reclaim Finish[i] = TRUE // process i completes go to Step 3
- 5. If *Finish*[*i*] = *TRUE* for all *i*, the system is in a safe state. If *Finish*[*i*] = *FALSE*, then process  $P_i$  is deadlocked.

Use Request here rather than Need in the safety algorithm <sup>23</sup>

#### Example: 1/2

	All	locati	on	R	eque	st	Available			
	X	Y	Z	X	Y	Ζ	X	Y	Ζ	
A	0	1	0	0	0	0	0	0	0	
B	2	0	0	2	0	2				
С	3	0	3	0	0	0				
D	2	1	1	1	0	0				
E	0	0	2	0	0	2				

- □ Suppose maximum available resource is [7,2,6] and the current state of resource allocation is shown above.
- □ *Is the system deadlocked?* No. We can run *A* first, making *Available*=[0,1,0].
- □ Then, we run *C*, making *Available*=[3,1,3]. This is followed by *D*, making *Available*=[5,2,4], and followed by *B* and *E*,

#### Example: 2/2



- Suppose *C* requests for one more resource *Z*. ■ Now, *A* can run, making *Available*=[0,1,0].
- □ However, none of *B*, *C*, *D* and *E* can run. Therefore, *B*, *C*, *D* and *E* are deadlocked!

#### The Use of a Detection Algorithm

#### **Frequency**

- If deadlocks occur frequently, then the detection algorithm should be invoked frequently.
- Once per hour or whenever CPU utilization becomes low (*i.e.*, below 40%). Low CPU utilization means more processes are waiting.

### How to Recover: 1/3

- When a detection algorithm determines a deadlock has occurred, the algorithm may inform the system administrator to deal with it. Of, allow the system to *recover* from a deadlock.
  There are two options.
  - **\***Process Termination
  - **Resource Preemption**
- **These two options are not mutually exclusive.**

# **Recovery: Process Termination: 2/3**

#### Abort all deadlocked processes

□ Abort one process at a time until the deadlock cycle is eliminated

#### **Problems:**

- Aborting a process may not be easy. What if a process is updating or printing a large file? The system must find some way to maintain the state of the file and printer before they can be reused.
- The termination may be determined by the priority/importance of a process.

#### **Recovery: Resource Preemption: 3/3**

- Selecting a victim: which resources and which processes are to be preempted?
- **Rollback:** If we preempt a resource from a process, what should be done with that process?
  - **\*** Total Rollback: abort the process and restart it
  - Partial Rollback: rollback the process only as far as necessary to break the deadlock.
- **Starvation:** We cannot always pick the same process as a victim. Some limit must be set.