

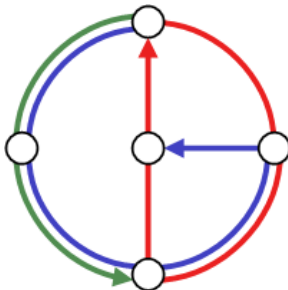
# MLS

## An Efficient Location Service for **Mobile** Ad Hoc Networks

**Roland Flury**

**Roger Wattenhofer**

*Distributed  
Computing  
Group*



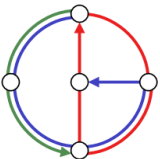
**ETH**

Eidgenössische Technische Hochschule Zürich  
Swiss Federal Institute of Technology Zurich

# Geographic Routing



- To each message, piggyback the position of the receiver
- The routing decision is solely based on this information
  - **Greedy forwarding:** A node forwards a message to its neighbor closest to the destination
  - **Face routing:** To surround routing voids, a message may be routed along the border of the hole



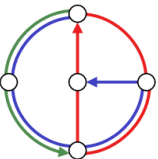
# Geographic Routing



- **Advantages of georouting**

- No routing tables, efficient and scalable
- No setup time, each new node can participate immediately
- Fully reactive (on demand) routing

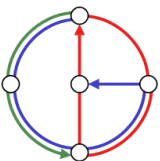
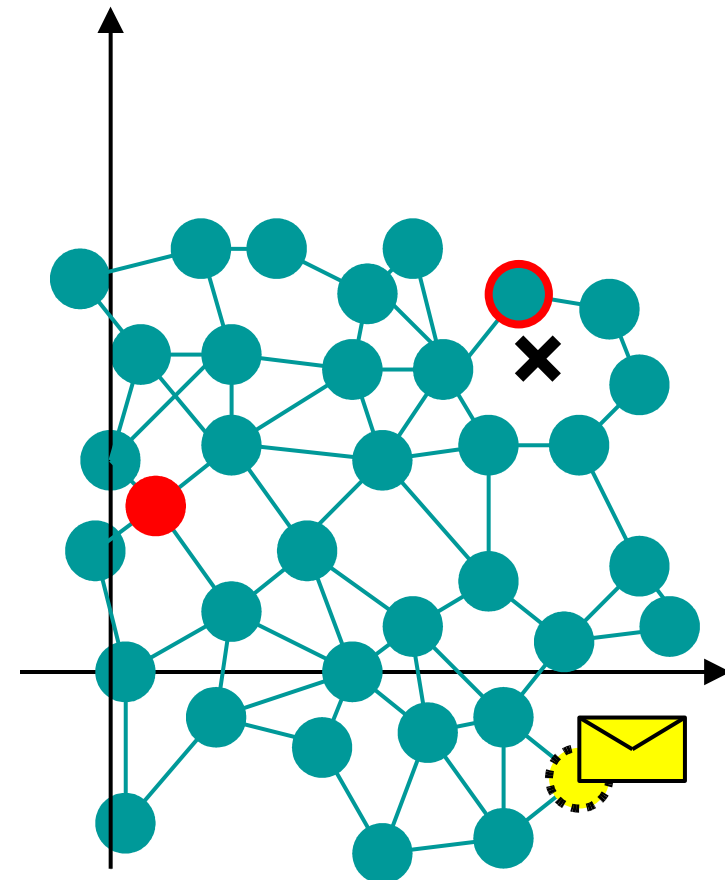
**... once the position  
of the destination is  
known**



# Location Service



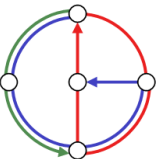
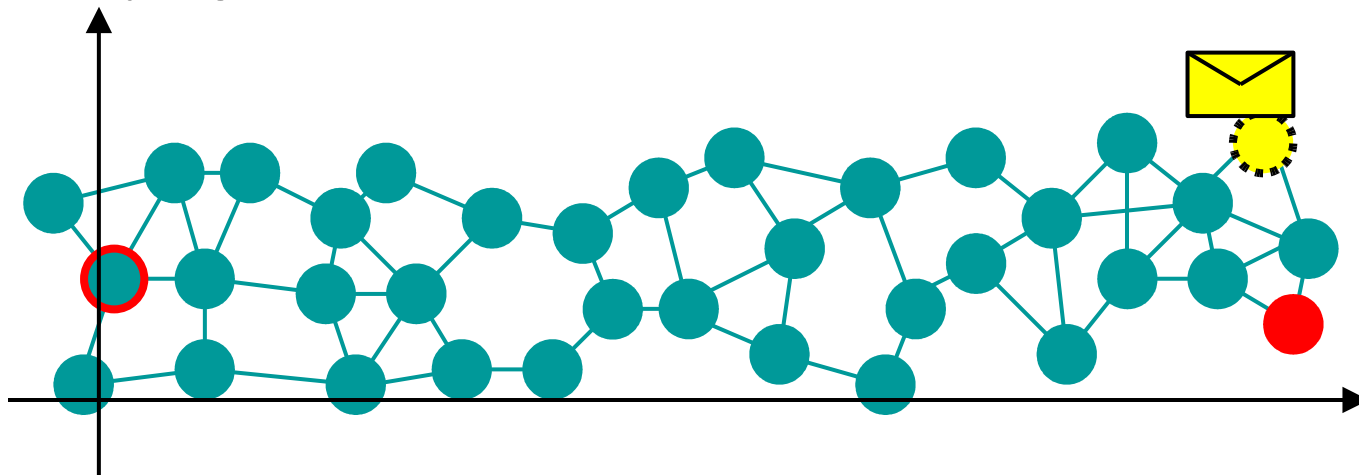
- **Q: How can a node determine the position of another node?**
- **Proactive distribution**
  - Each node broadcasts its position
  - VERY expensive
- **Home based** location service
  - Each node has an associated place (its home) where it stores its location
  - The place is determined by the hash value of the node's ID
  - Any node can determine this place
  - This is a **GHT** (Geographic Hash Table)



# GHT: Home Based Location Service

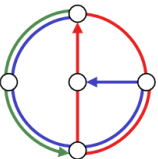
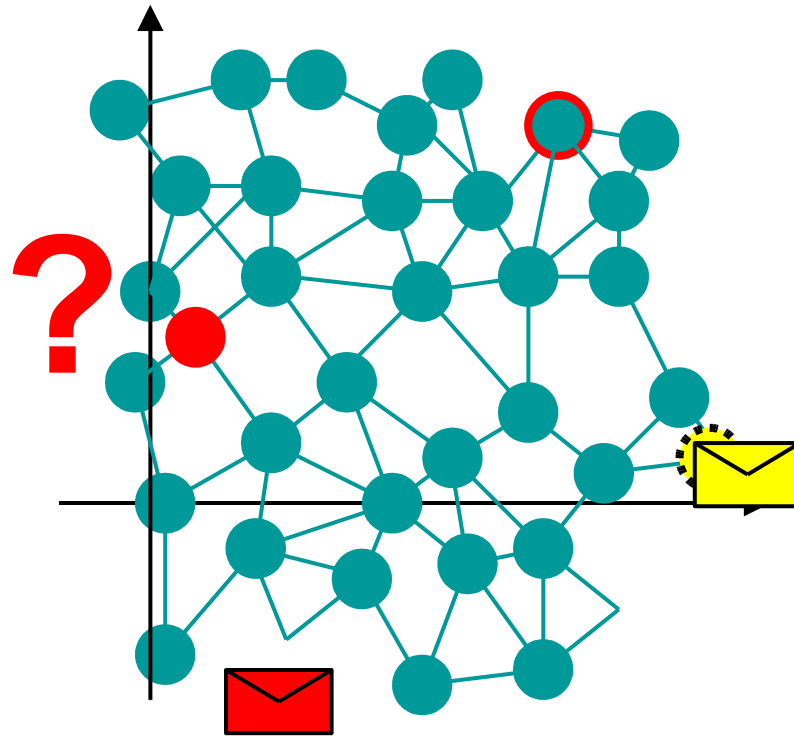


- Each node has a single location server
  - Chosen at a random position
- Good load balancing
  - Each node has to store location information only for a few nodes
- Arbitrary high stretch:



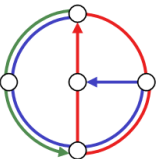
# Mobility

- Mobile nodes complicate location services tremendously
- The **position of a node cannot be known exactly**, as it may change continuously
- Any location information has to be considered **stale**
  - Lookup of position not wise, rather route messages through location server



# Some Related Work in the field of Location Services

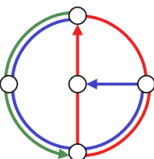
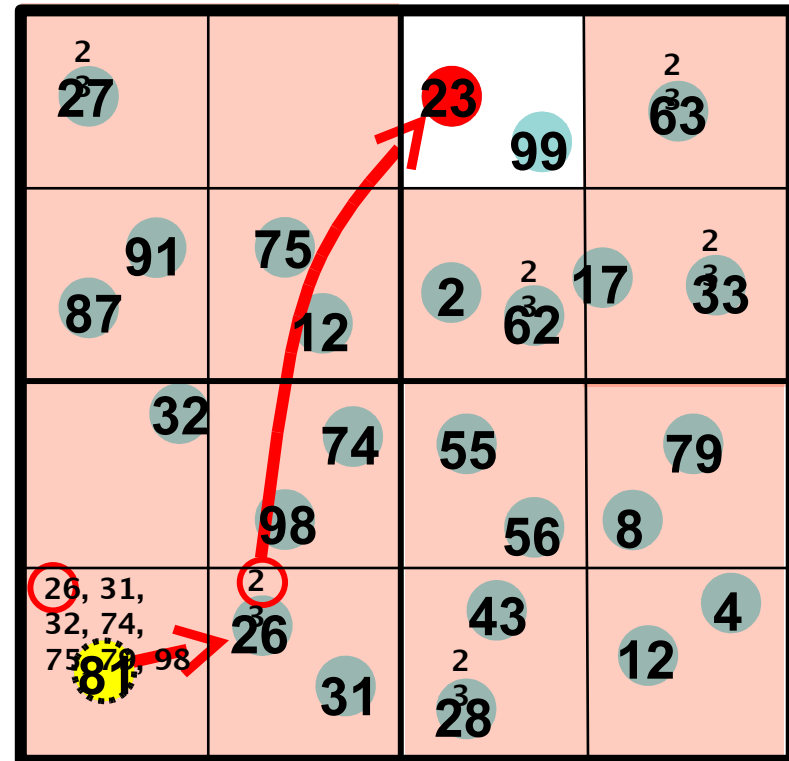
- **LLS**: “*LLS: A Locality Aware Location Service for Mobile Ad Hoc Networks*” by Abraham et al. @ DIALM-POMC 2004
- **GLS**: “*A Scalable Location Service for Geographic Ad Hoc Routing*” by Li et al. @ MobiCom 2000
- **DLM**: “*A Scalable Location Management Scheme in Mobile Ad Hoc Networks*” by Xue et al. in LCN 2001
- **HIGH-GRADE**: “*Enhancing Location Service Scalability with High-Grade*” by Yu et al. @ MASS 2005
- “*Scalable Ad Hoc Routing: The Case for Dynamic Addressing*” by Eriksson et al. @ InfoCom 2004
- “*Geographic Routing without Location Information*” by Rao et al. @ MobiCom 2003
- “*Topology Independent Location Service for Self-Organizing Networks*” by Rezende et al. @ MobiHoc 2005



# Related Work (Excerpt) - GLS



- **GLS:** “A Scalable Location Service for Geographic Ad Hoc Routing” by Li et al. @ MobiCom 2000
- **Lookup cost:** Size of the biggest surrounding square (level)
- **Publish cost:** not bounded





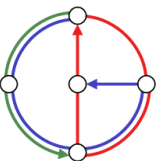
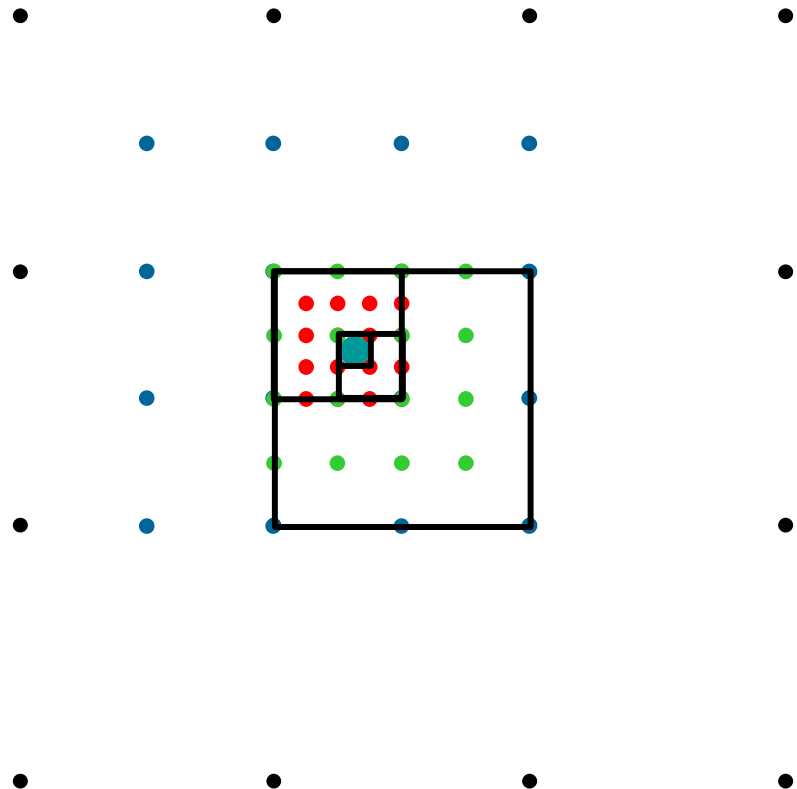
# Related Work (Excerpt) - LLS



- **LLS:** “*LLS: A Locality Aware Location Service for Mobile Ad Hoc Networks*” by Abraham et al. @ DIALM-POMC 2004

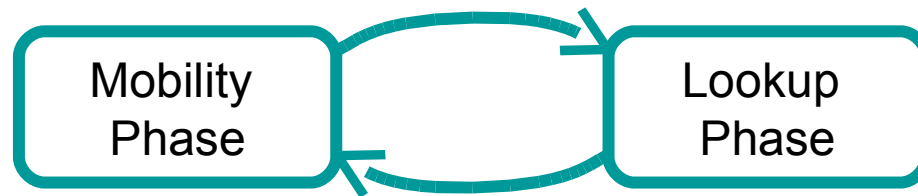
- **Lookup cost:**  $O(d^2)$

- **Publish cost (amortized):**  
 $O(d \log d)$



# Mobility revisited

- GLS and LLS support mobile nodes, but not **concurrent lookup and mobility**
- Existing solutions assume that mobility and lookups do not interfere

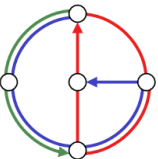


The nodes are mobile and update their location servers

**XOR**

The nodes perform lookups

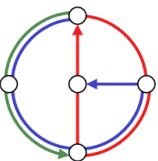
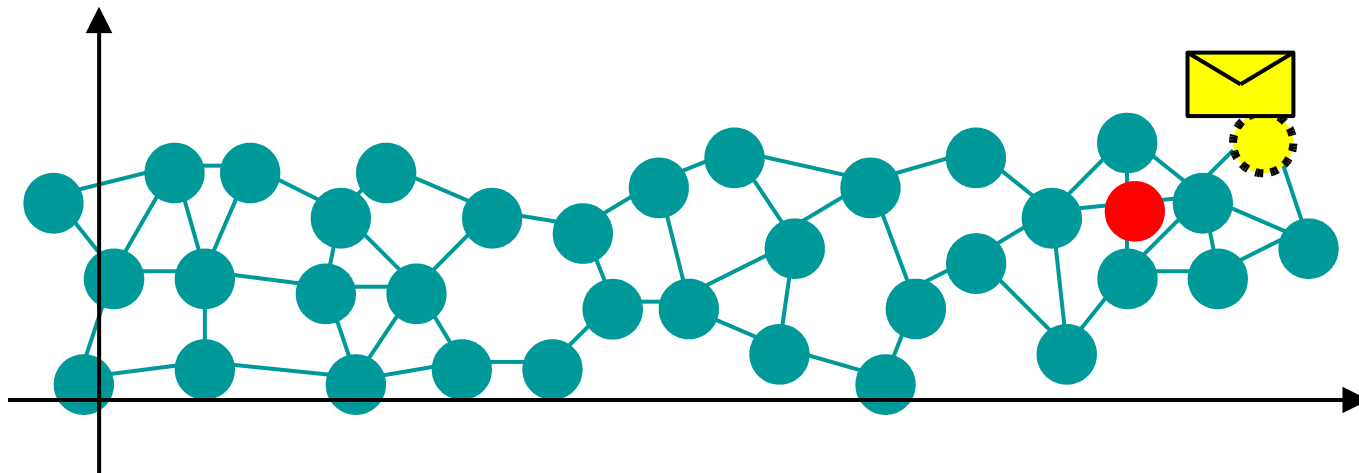
- That's clearly not what we expect from a **MANET!**
  - Nodes cannot move freely
  - Lookups / routing cannot happen concurrently
  - Synchronization would be required to switch between the two phases



# Mobility – but limited



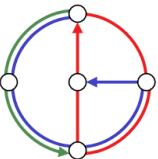
- Nodes may not move arbitrarily fast!
  - If a node moves faster than the **message propagation speed**, no routing algorithm can ensure delivery
- Thus, we must **limit the maximum node speed**
  - Maximum node speed can be expressed as a function of the message propagation speed of the underlying routing algorithm



# Outline

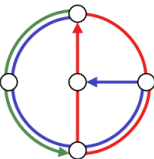


- **Motivation** for building location services
- **Mobility** and its issues
- **Related work**
- **MLS** our contribution
- **Model**
- **Algorithm & Analysis**
- **Conclusion**



# MLS – Location Service for Truly **Mobile** Nodes

- The lookup service works despite of **concurrent mobility**
  - Nodes may move freely at any time and anywhere
  - Lookup and routing requests may execute at any time
- Routing is performed through the lookup mechanism
  - No stale location information
- **Lookup / routing overhead:** close to optimal
  - Routing to a node costs  $O(d)$ , where  $d$  is the distance
- Moderate **publish overhead** due to mobility
  - Amortized bit-meter cost is  $O(d \log d)$  for moving a distance  $d$
- Quite **fast moving nodes!**
  - Nodes may move up to **1/15 of the message propagation speed**
  - On arbitrary paths



# Model



- **Deployment Area**

- Nodes populate land areas
- Lake denote holes
- Connected graph, no islands

- **Connectivity**

- $n_1, n_2$  are connected if  $d(n_1, n_2) \leq r_{\min}$

- **Density**

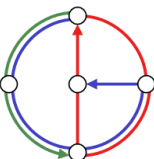
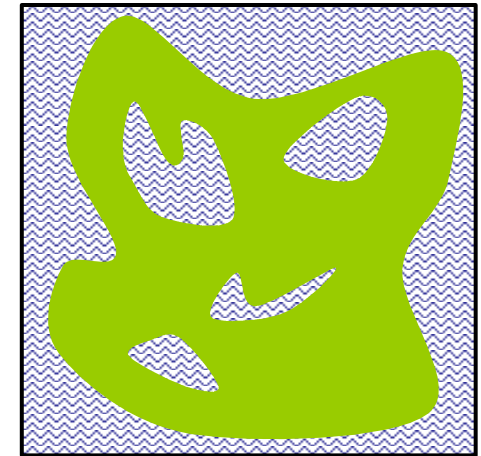
- For any point on land, there exists a node at most  $r_{\min} / 3$  away
- Thus, relatively dense node deployment

- **Node Equipment**

- Position module (GPS, Galileo, local system, ...)
- Communication module

- **Underlying Routing**

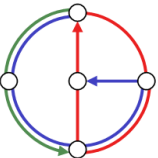
- Given a destination position  $p_t$ , we can route a message in  $\eta d(p_s, p_t)$  from the sender position  $p_s$  to  $p_t$



# Outline

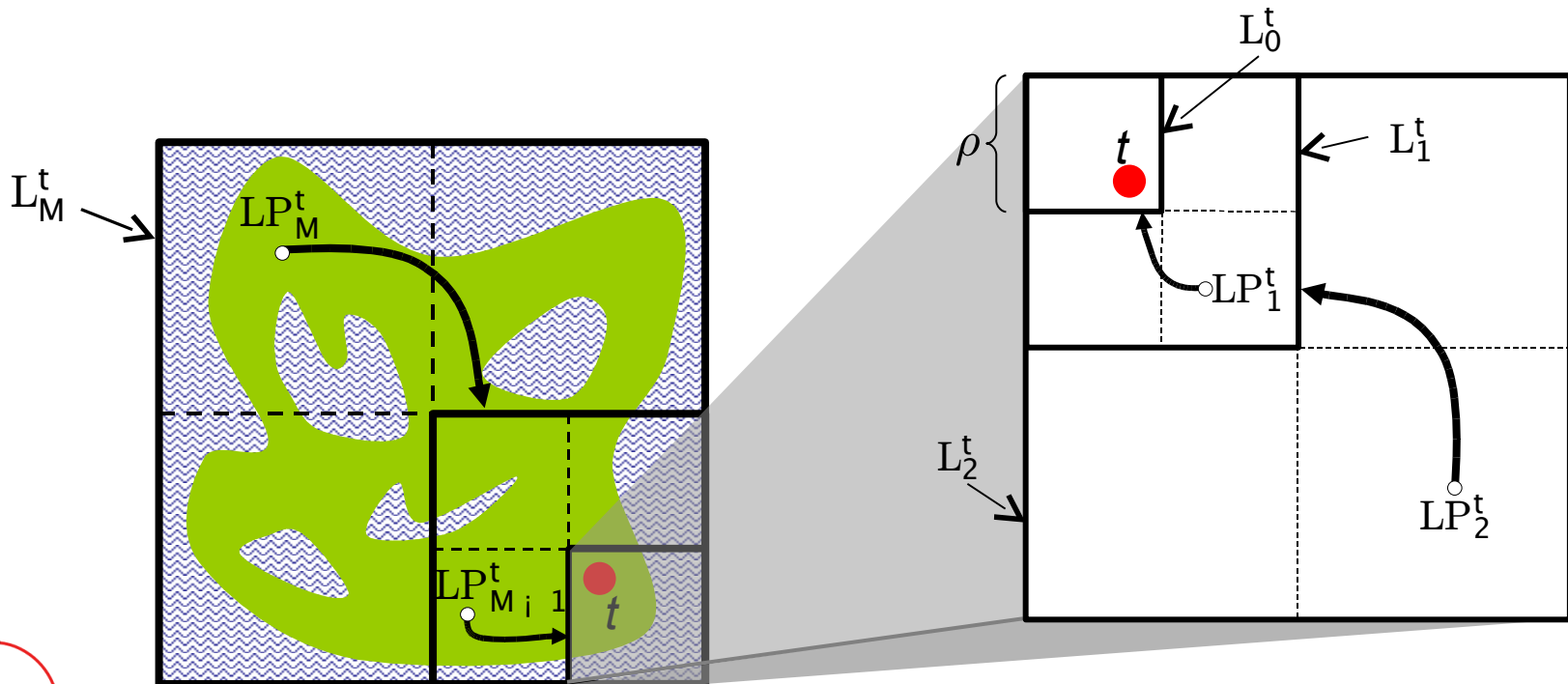


- **Motivation** for building location services
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- **Conclusion**



# Selection of Location Servers

- Each node builds a hierarchy of location servers that are located in exponentially increasing areas around the node.
  - Top **level** surrounds entire world
  - Each level is divided in 4 sub-squares
  - A **level pointer** points to the next smaller level that surrounds  $t$
  - The position of the level pointer is determined by hashing the ID of  $t$





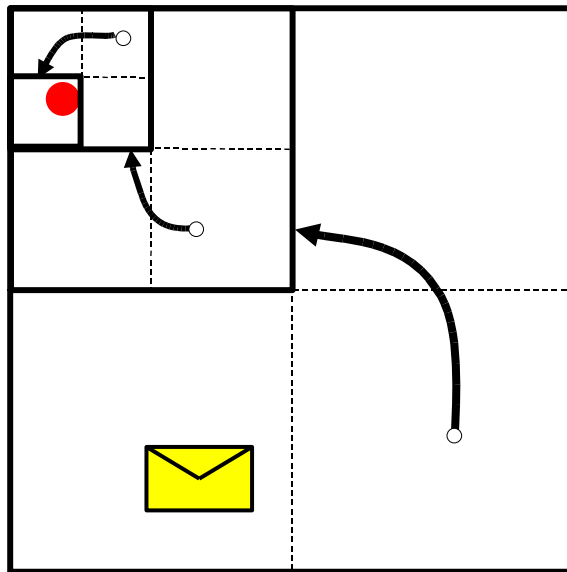
# Routing in MLS



- Routing in MLS consists of two phases

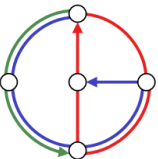
- 1) Find a Location Pointer of the destination
- 2) Recursively follow the Location Pointers

- The second step pretty easy:



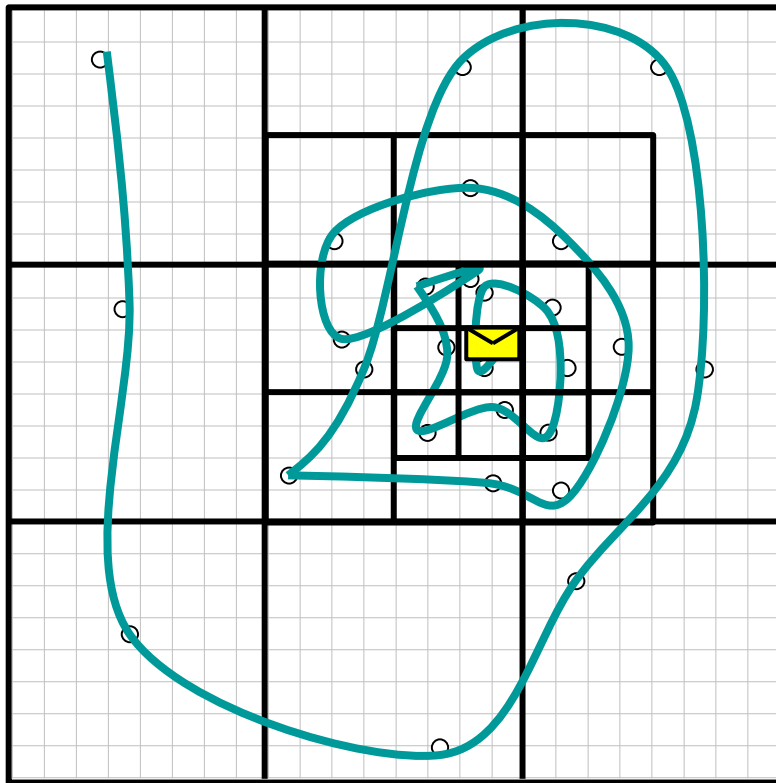
## Performance

If the destination is  $d$  away from sender, the lookup path is  $O(d)$ .



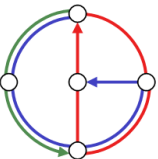
# How to find a Location Pointer

- First, the sender assumes that the destination is in its vicinity
- While the lookup request fails to find a location pointer, it increases the search area



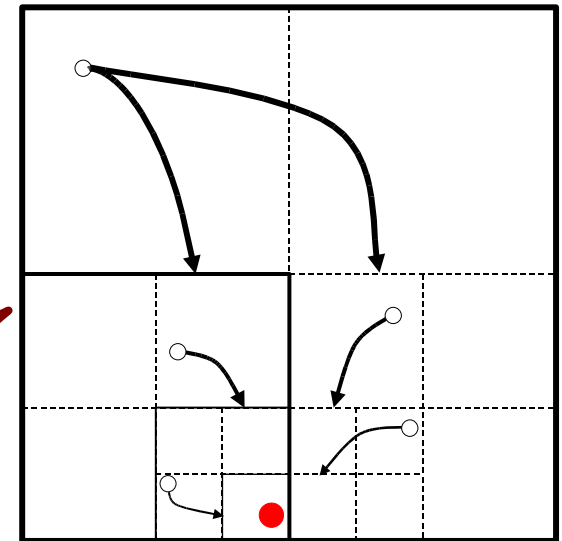
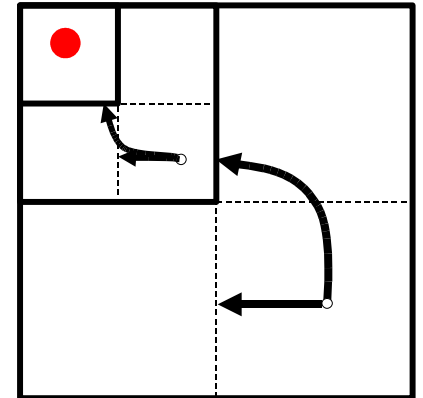
## Performance

If the destination is  $d$  away from sender, the lookup path to *find a first location pointer* is  $O(d)$ .

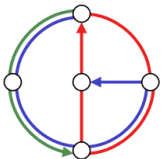


# Supporting Mobility

- A location pointer only needs to be updated when the node leaves the corresponding sub-square.
- *Most of the time*, only the closest few location pointers need to be updated due to mobility
- **Not enough to guarantee low publish overhead!**
  - If node oscillates over grid-boundary of several layers, *many* location pointers need to be updated.



**Unbounded publish cost!**

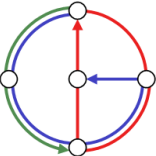
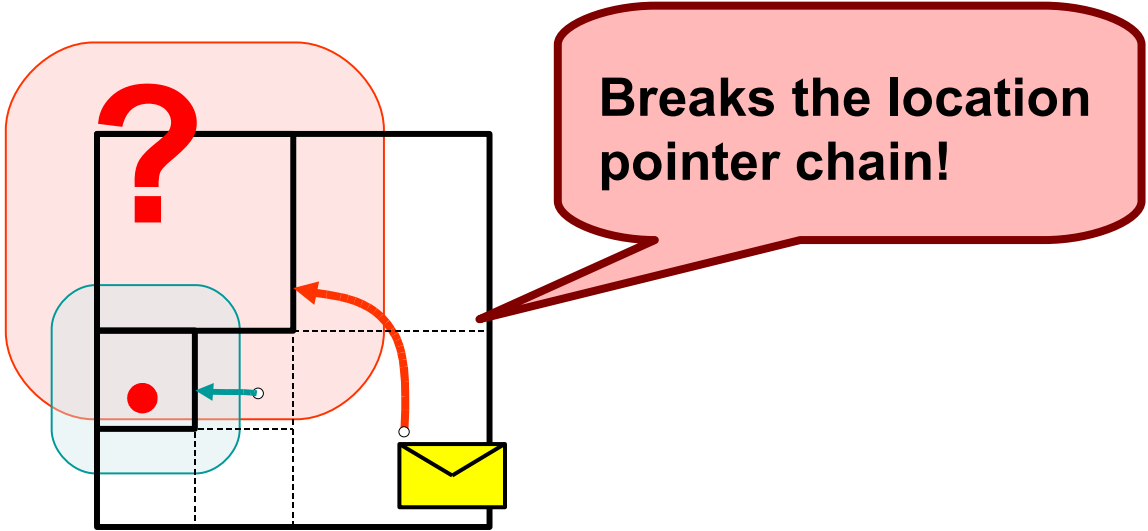


# Lazy Publishing



- To overcome exorbitant publish cost due to oscillating  $\epsilon$ -moves:

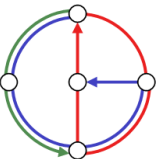
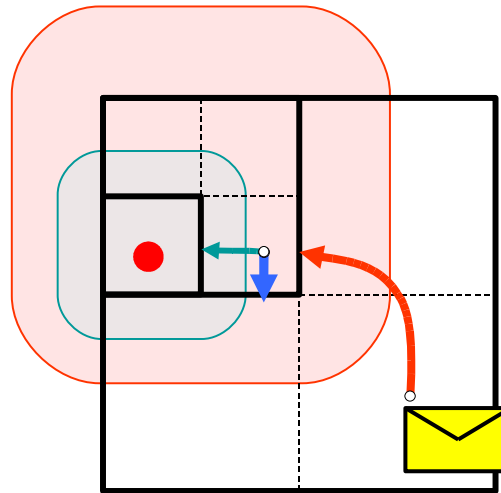
**Only update a location pointer if the node has moved away quite a bit**



# Lazy Publishing with Forwarding Pointers

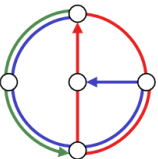
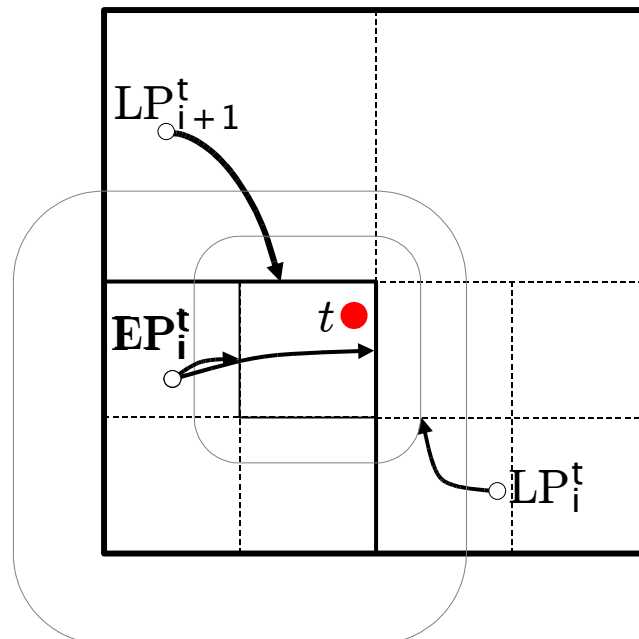


- To repair the lookup path, add a **forwarding pointer** that points to the neighboring level that contains the location pointer.



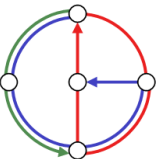
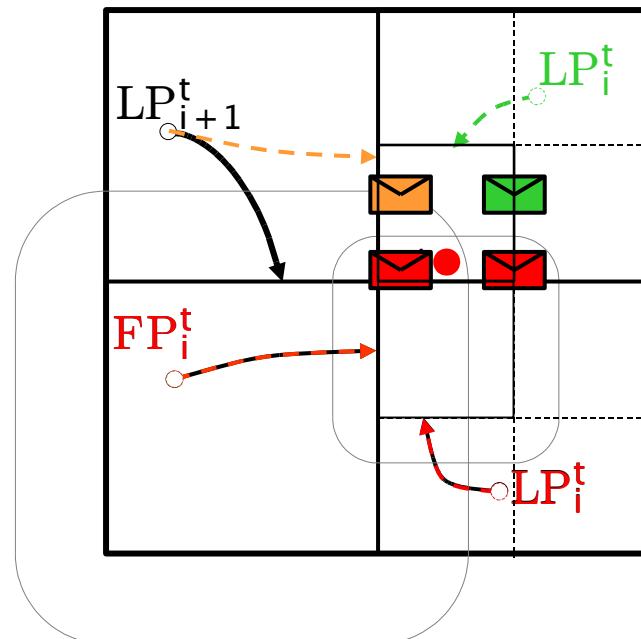
# Supporting Concurrency

- Allowing for **concurrent lookup requests and node mobility** is somewhat tricky



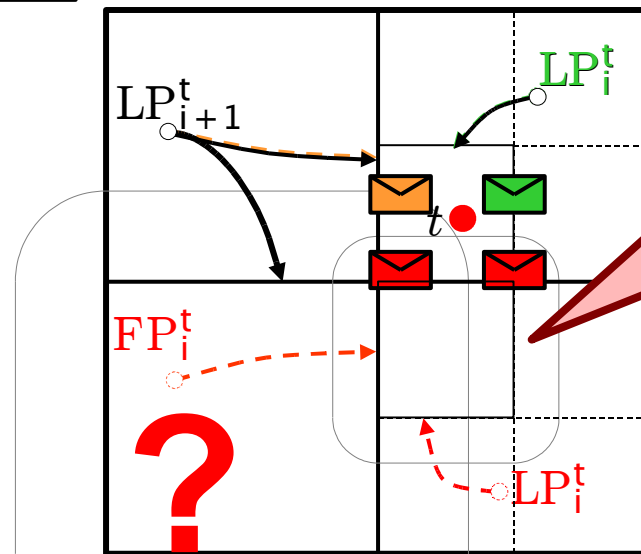
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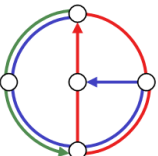


# Supporting Concurrency

- Allowing for **concurrent lookup requests and node mobility** is somewhat tricky
  - Especially the *deletion* of location pointers and forwarding pointers
- **Routing of messages needs time**
  - Sending a message to the next location pointer
  - Sending command messages to update / delete / create a location pointer



**Note:**  
These problems arise independently of the node speed.






# Supporting Concurrency – TFP

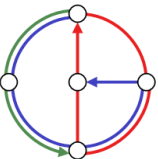


- Solution to overcome the concurrency issue:

**Do not delete a location or forwarding pointer,  
but replace it with a  
Temporary Forwarding Pointer (TFP)**

- A temporary pointer  redirects a lookup to the neighbor level where the node is located.

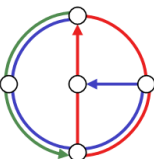
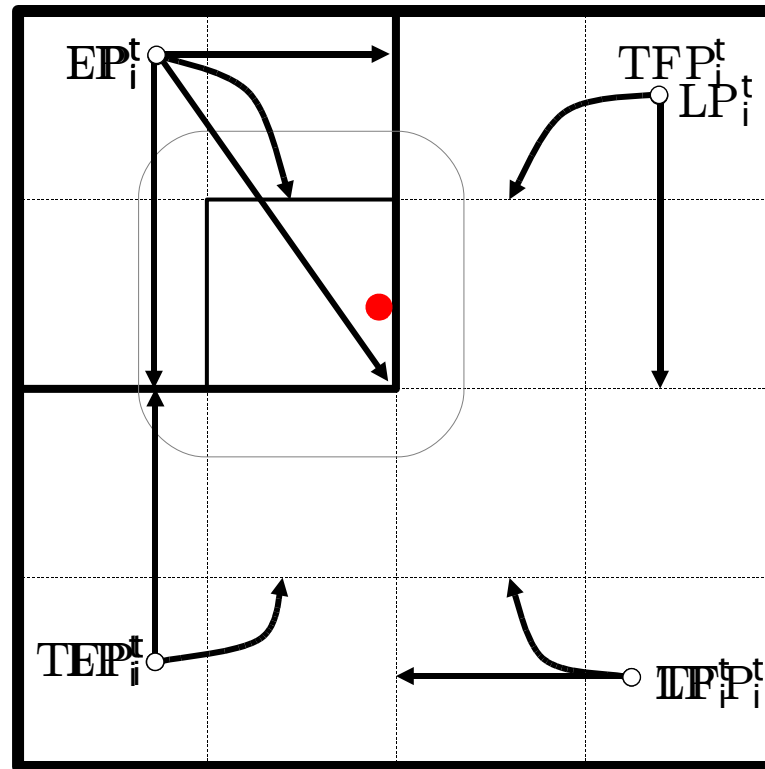
**TFP are temporary  
and must be  
removed after a  
well known time.**



# Speeding



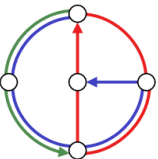
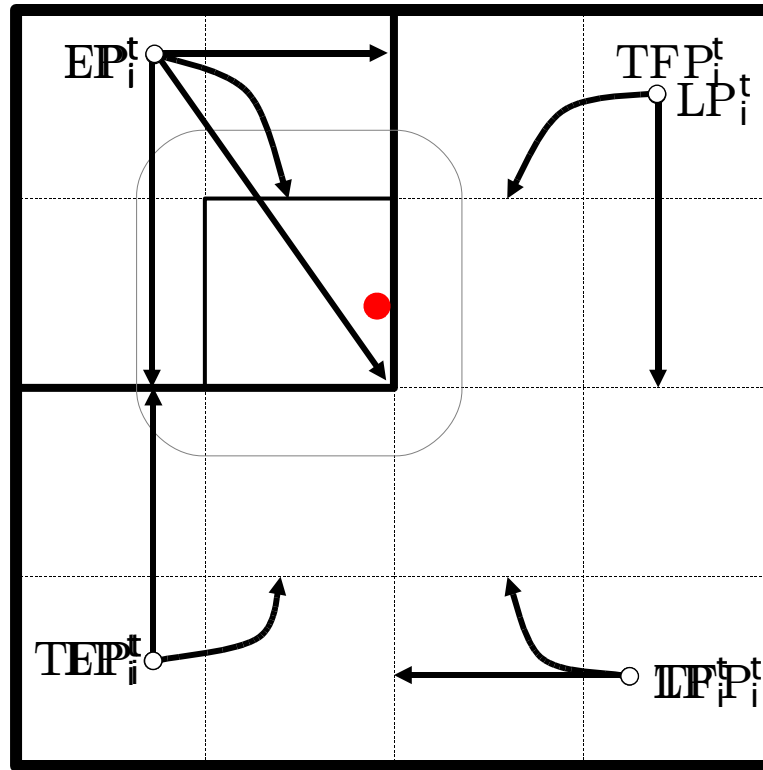
- A mobile node may generate many forwarding pointers while a lookup searches for it
  - If the lookup is not fast enough, it permanently follows forwarding pointers



# Speeding



- A mobile node may generate many forwarding pointers while a lookup searches for it
  - If the lookup is not fast enough, it permanently follows forwarding pointers



# Performance of MLS

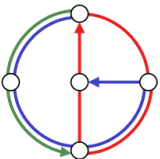


- The **maximum node speed** depends on several parameters
  - Min. speed of underlying routing
  - Lazyness in lazy publishing
  - How long we are willingly to follow temporary and forwarding pointers of a moving node
- [...] Without lakes, the maximum node speed must be bounded by a fraction of the minimum message speed of the underlying network

**Please see paper for details...**

$$v_{\text{node}} \leq \frac{v_{\text{msg}}}{15}$$

- Despite of this relatively high node speed
  - **Lookup cost is  $O(d)$**
  - **Amortized publish cost is  $O(d \log d)$**

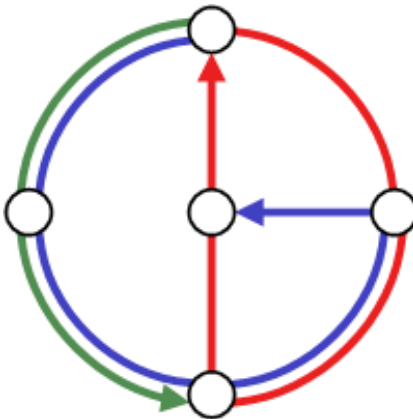




# Thank you!

## Questions / Comments?

**D**istributed  
**C**omputing  
**G**roup

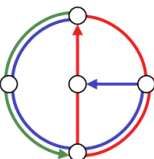


**Roland Flury**  
**Roger Wattenhofer**

# BACKUP - - - - -

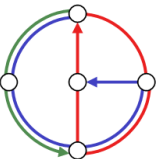


- Publish Algorithm
- Lookup Algorithm
- Nomenclature
- GLS (Related work)
- LLS (Related work)
- LLS WC



# Publish Algorithm

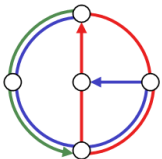
1 **if**( $\delta_i^t \geq \alpha \cdot \rho \cdot 2^i$ ) {  
2     **if**( $i > 0$ ) {change  $FP_i^t$  in  $*LP_{i+1}^t$  to  $TFP_i^t$ ;}  
3     **if**( $LP_{i+1}^t \in L_{i+1}^t$ ) {  
4         change  $LP_{i+1}^t$  to point to  $L_i^t$ ;  
5     } **else** {  
6         **if**( $LP_{i+1}^t \in *LP_{i+2}^t$ ) {  
7             change  $LP_{i+1}^t$  to  $FP_{i+1}^t$  that points to  $L_{i+1}^t$ ;  
8         } **elseif**( $L_{i+1}^t = *LP_{i+2}^t$ ) {  
9             change  $LP_{i+1}^t$  to  $TFP_{i+1}^t$  that points to  $L_{i+1}^t$ ;  
10         } **else** {  
11             change  $LP_{i+1}^t$  to  $TFP_{i+1}^t$  that points to  $L_{i+1}^t$ ;  
12             change  $FP_{i+1}^t$  to point to  $L_{i+1}^t$ ;  
13         }  
14         on  $L_{i+1}^t$ , add  $LP_{i+1}^t$  that points to  $L_i^t$ ;  
15     }  
16     **if**( $i > 0$  and  $LP_i^t \notin L_i^t$ ) {  
17         add  $FP_i^t$  on  $L_i^t$  that points to  $L_i \ni LP_i^t$ ;  
18     }  
19 }



# Lookup Algorithm



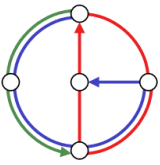
- 1 **if**( $t \in L_0^s \cup (L_0^s)^8$ ) { **exit**(); }
- 2 **for**( $i=1$ ; **true**;  $i++$ ) {
- 3     **if**( $P_i^t \in L_i^s \parallel P_i^t \in (L_i^s)^8$ ) {
- 4          $p = P_i^t$ ;
- 5         **break**;
- 6     }
- 7 }
- 8 Follow  $p$  until  $LP_1^t$  is reached.
- 9 Route to a node closest to an arbitrary point on land in  $*LP_1^t$ .
- 10 Forward to  $t$ .



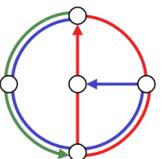
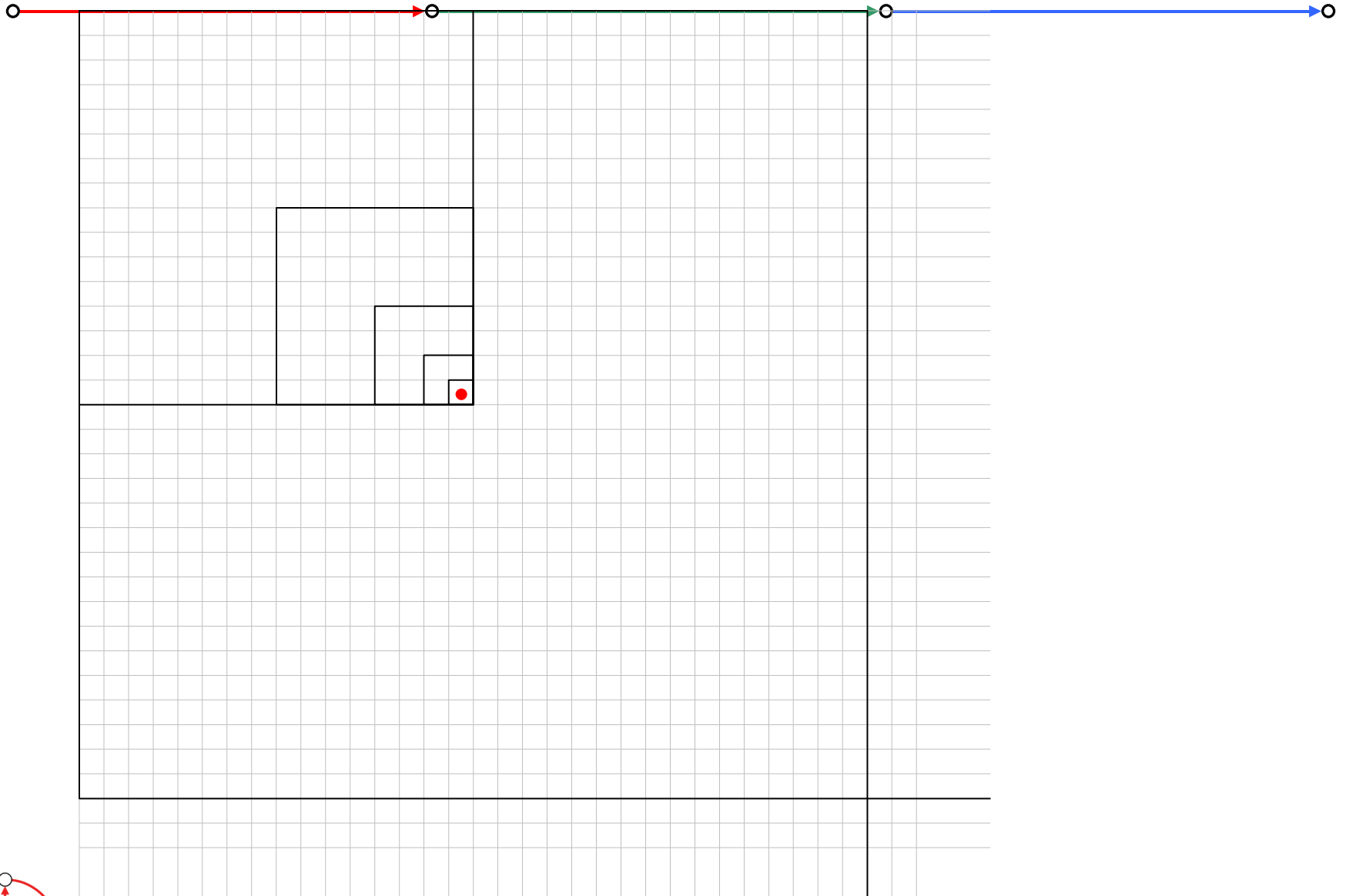


# Nomenclature

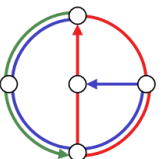
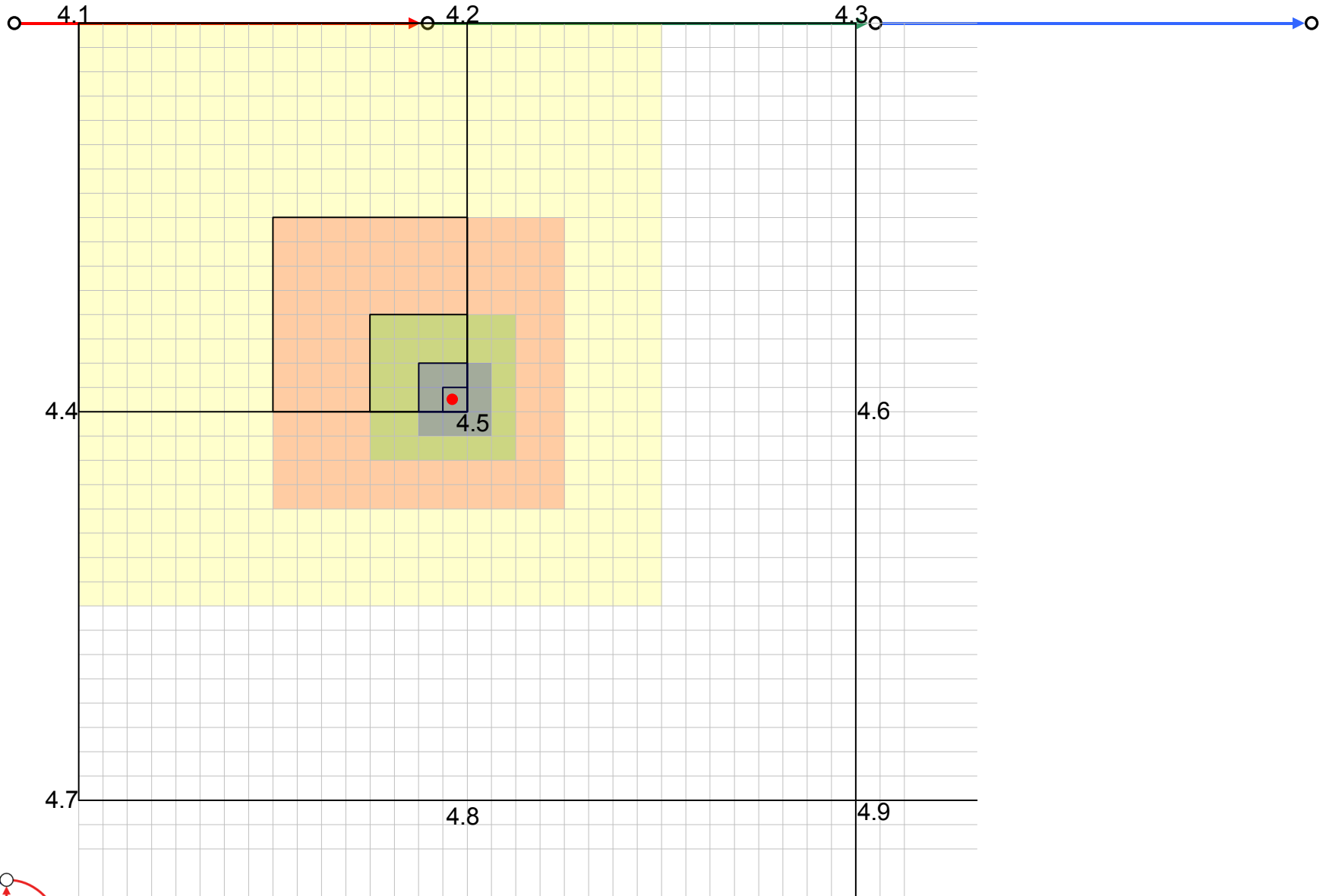
$L_i^t$	Level that contains $t$ with side-length $\rho \cdot 2^i$
$(L_i^s)^8$	The 8 surrounding squares of $L_i^s$
$LP_i^t$	Level pointer on $L_i$ for node $t$ ; points to $L_{i-1}$
$*LP_i^t$	The $L_{i-1}$ where $LP_i^t$ points to
$\delta_i^t$	distance of a node $t$ to $*LP_{i+1}^t$
$FP_i^t$	Forwarding pointer if $LP_i^t \notin *LP_{i+1}^t$
$*FP_i^t$	The $L_i$ where $*FP_i^t$ points
$TFP_i^t$	Temporary forwarding pointer, before a pointer to $t$ is removed
$*TFP_i^t$	The $L_i$ where $TFP_i^t$ points
$TTL_i$	Time to live of a $TFP_i$
$v_{max}^{node}$	Max. speed of nodes
$r_{min}$	Min. communication range of a node
$\lambda$	Min. distance to a node from any land point
$\rho$	Side length of $L_0$ ; $\rho = \lambda/\sqrt{2}$
$M$	$L_M$ surrounds the entire world
$\alpha$	When $\delta_i^t \geq \alpha \cdot \rho \cdot 2^i$ , $LP_{i+1}^t$ is updated
$\beta(\beta_T)$	Max. number of forwarding hops to reach $LP_i^t$ from a $FP_i^t$ ( $TFP_i^t$ )
$\gamma$	See Lemma 8.2
$\eta$	Routing overhead to route to a given position



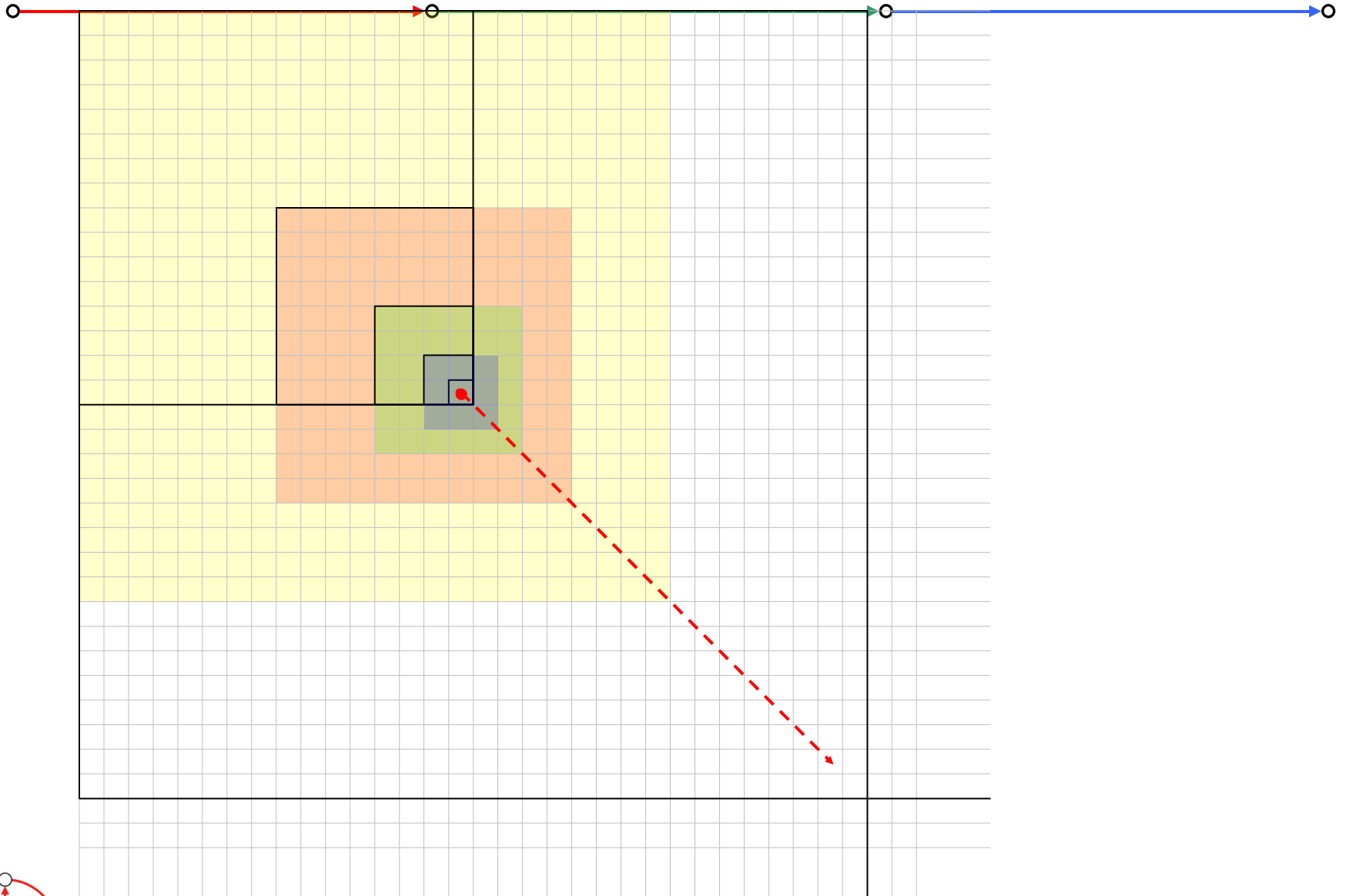
# LLS Worst Case



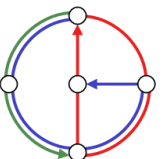
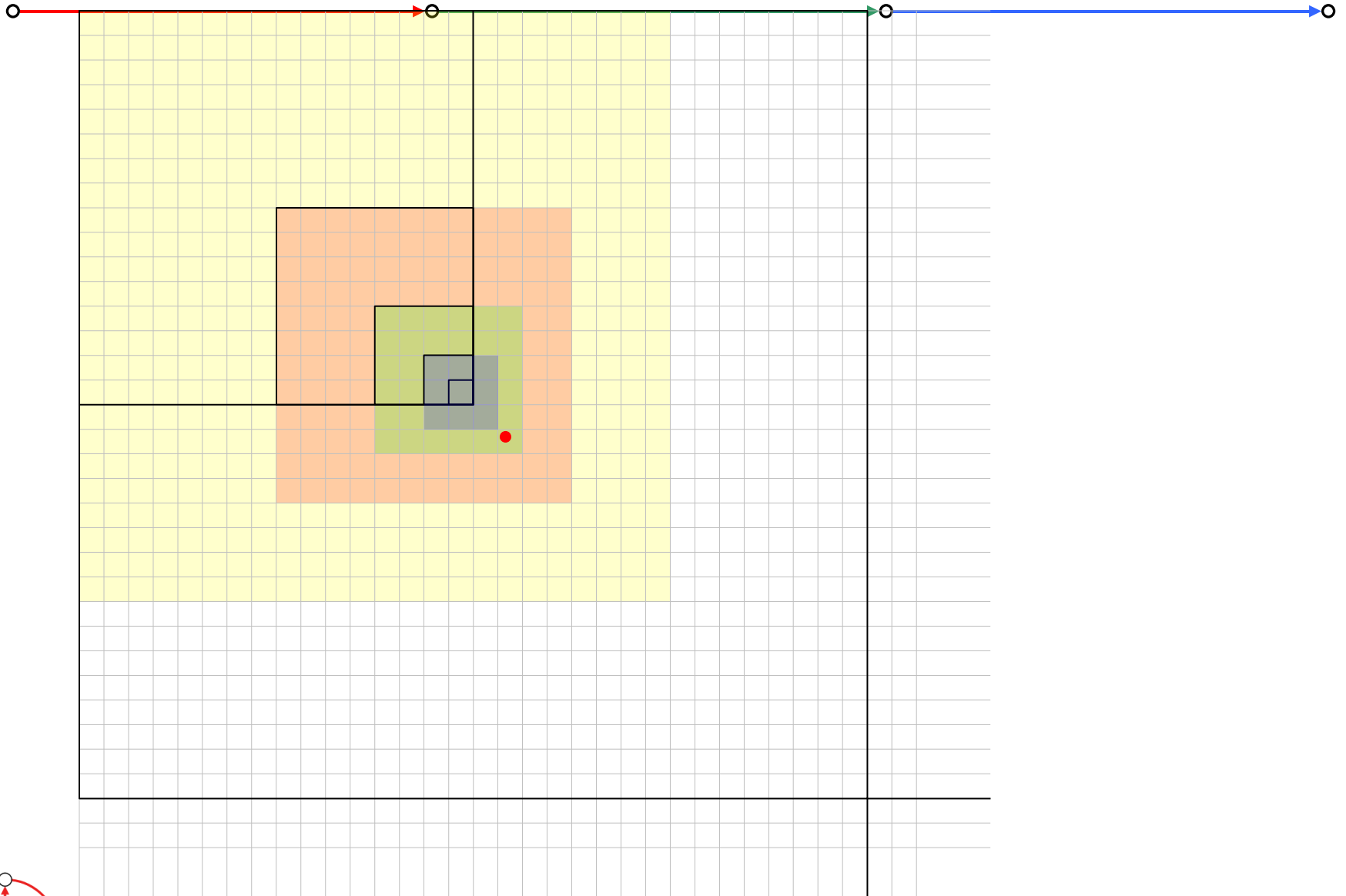
# LLS Worst Case



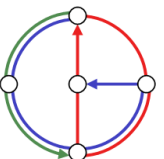
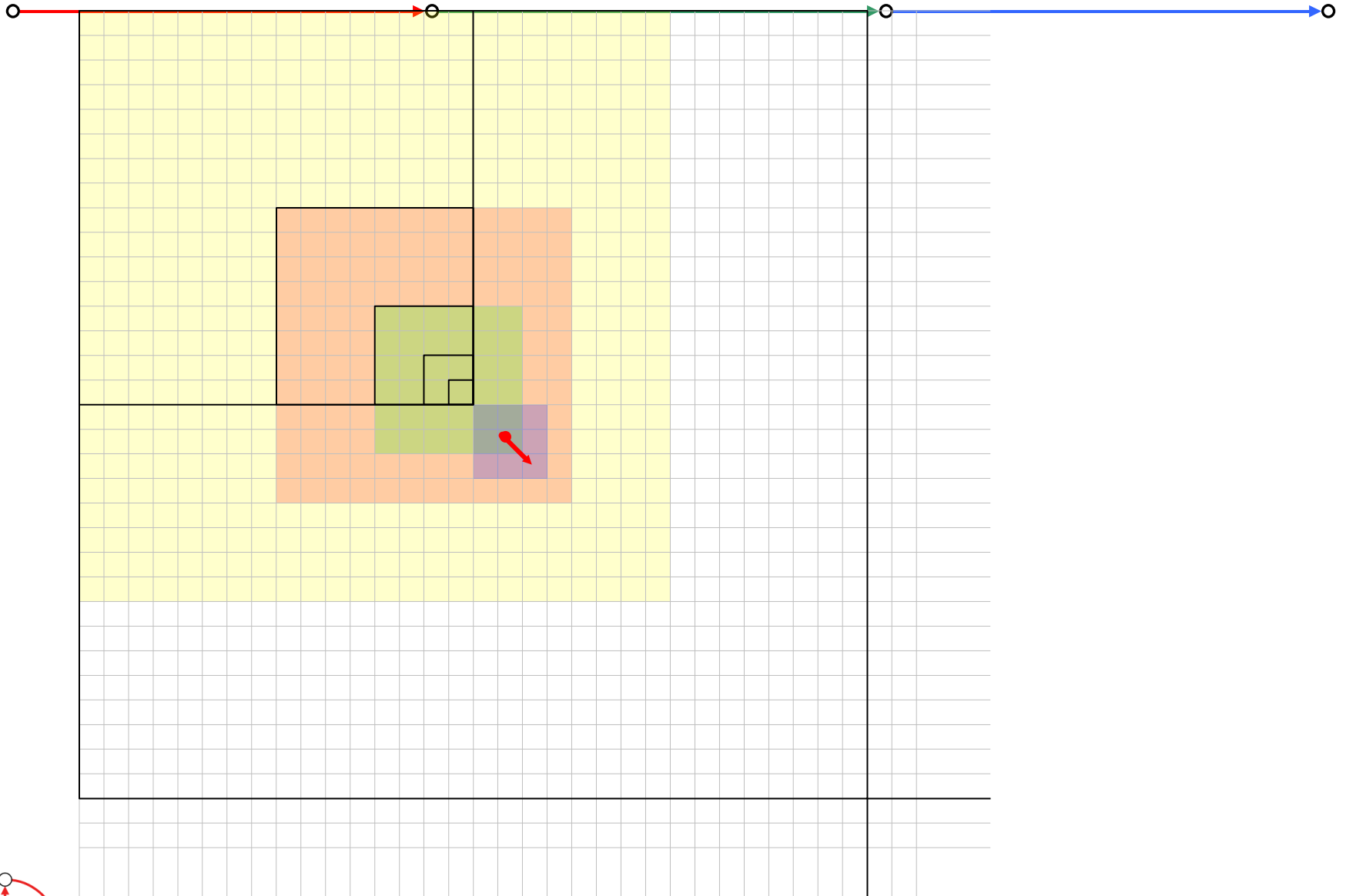
# LLS Worst Case



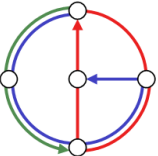
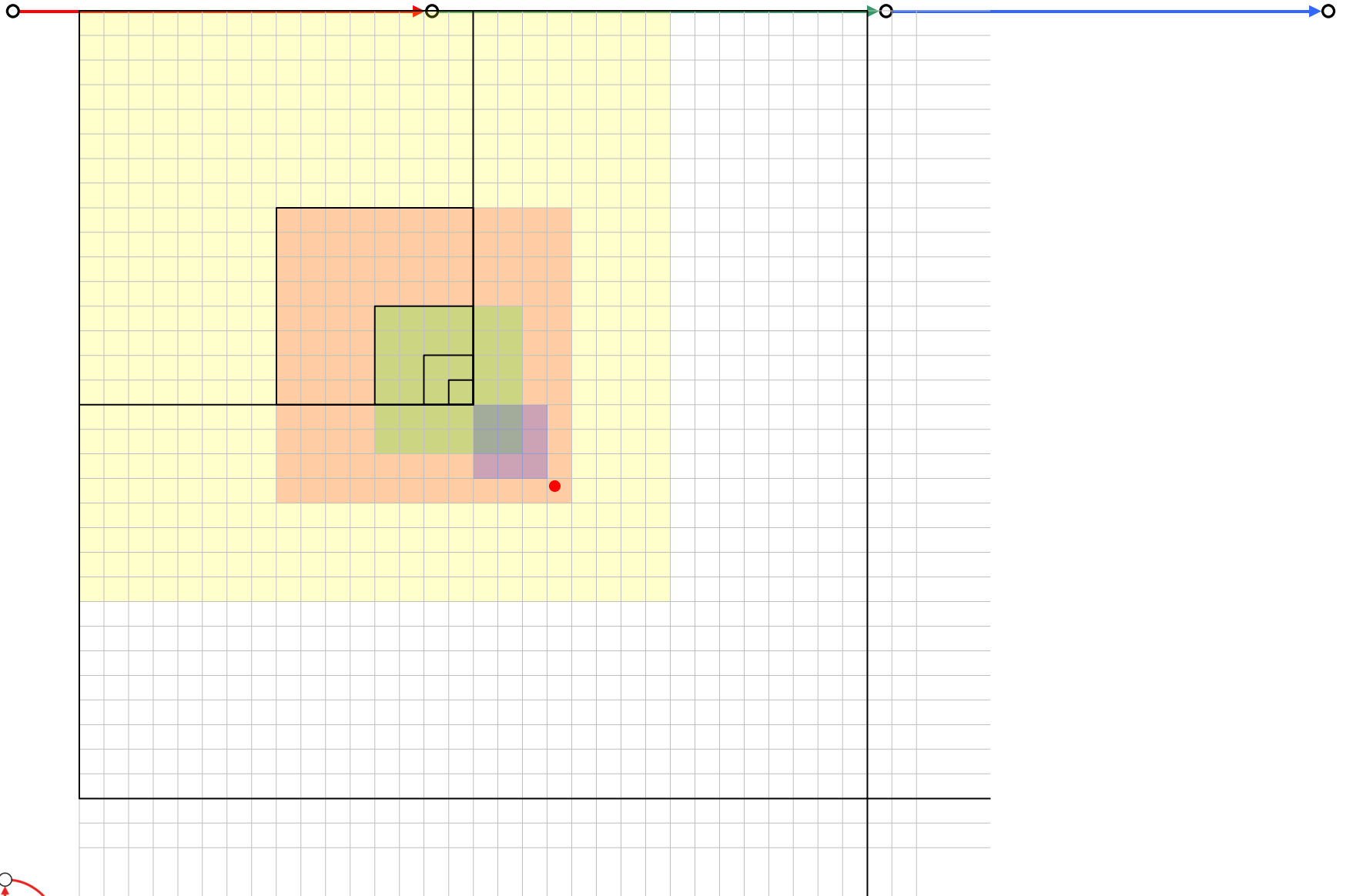
# LLS Worst Case



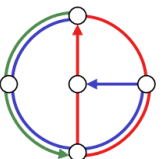
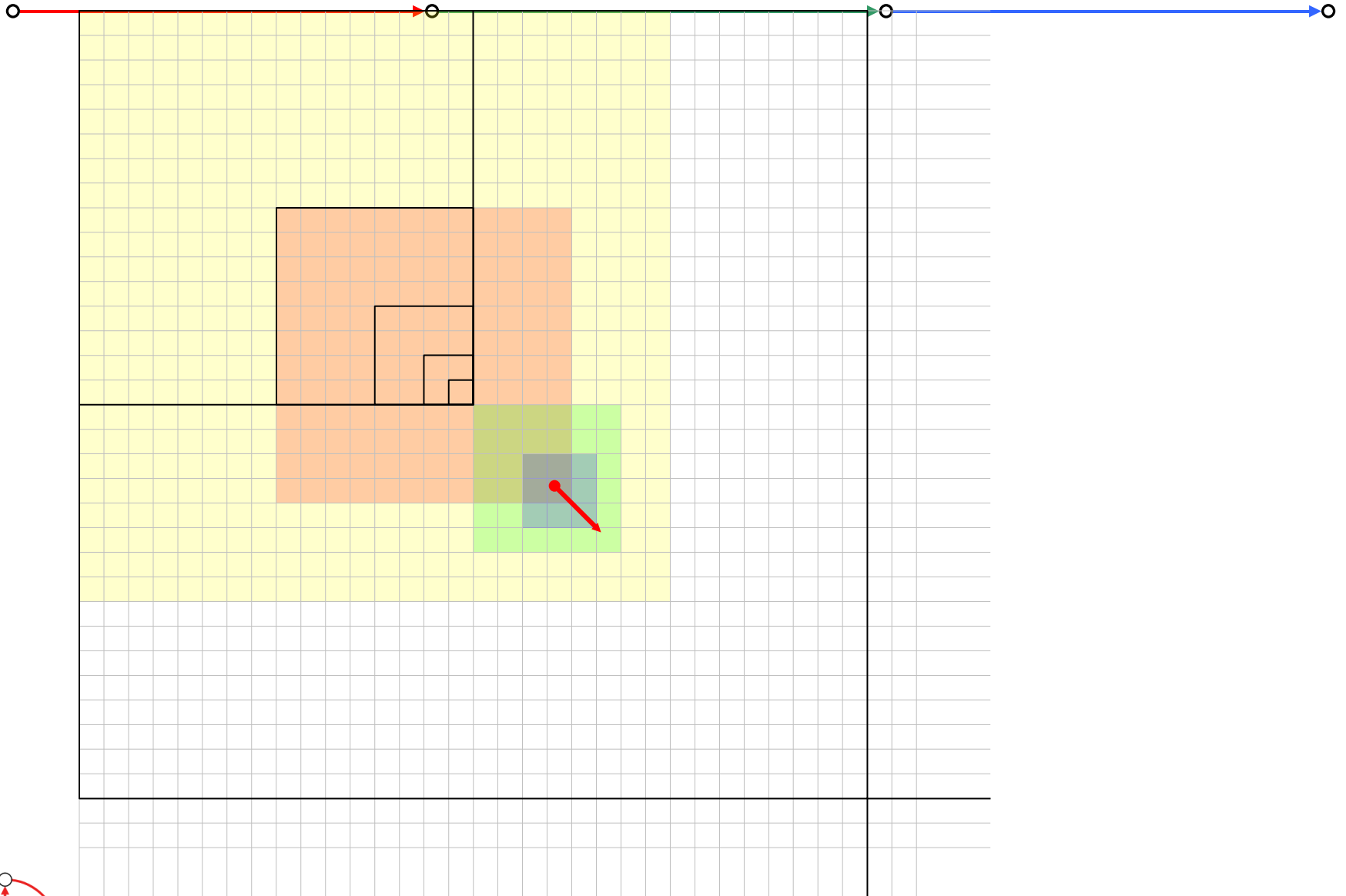
# LLS Worst Case



# LLS Worst Case

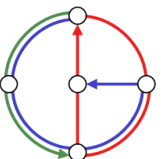
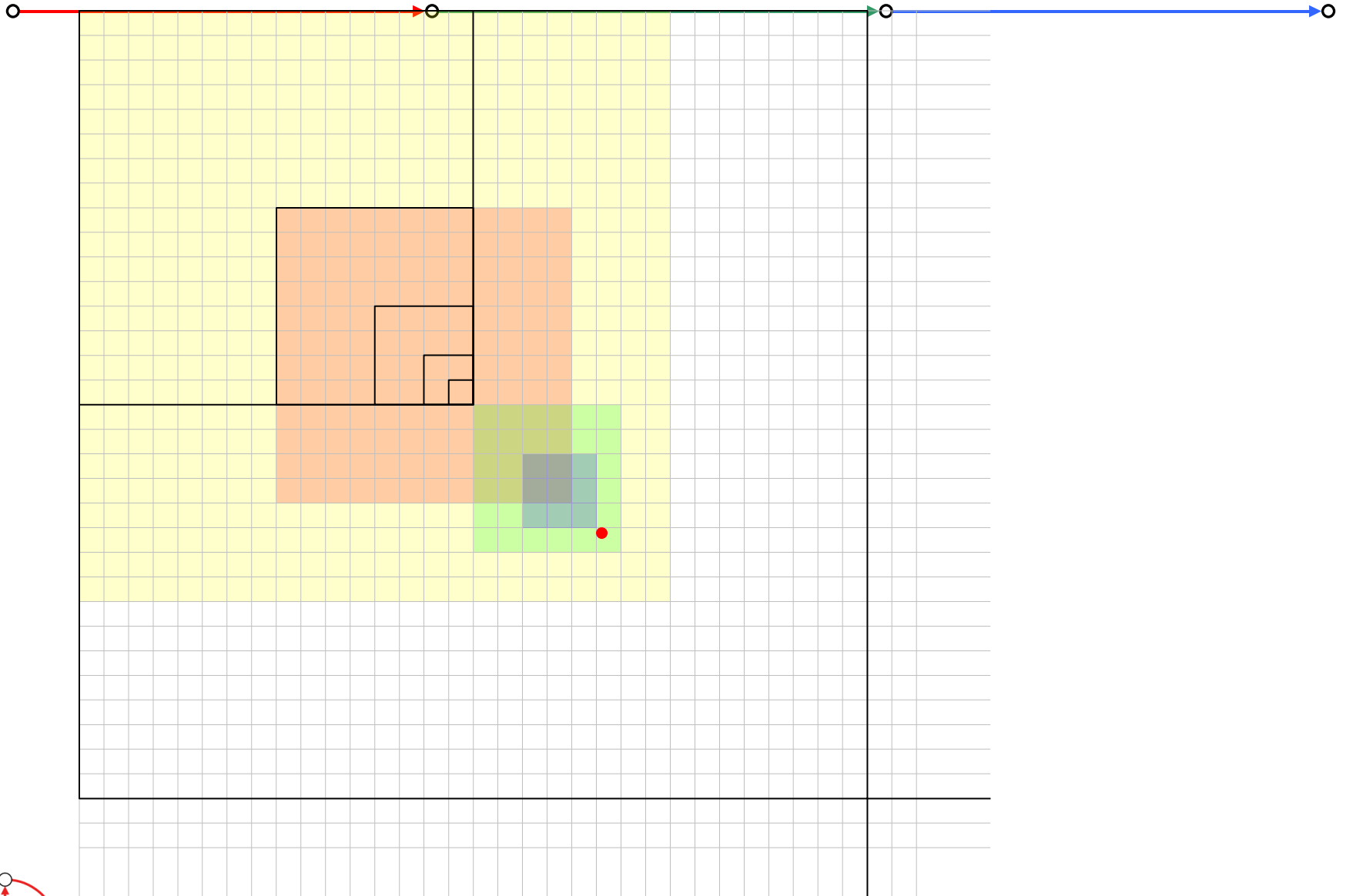


# LLS Worst Case

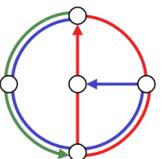
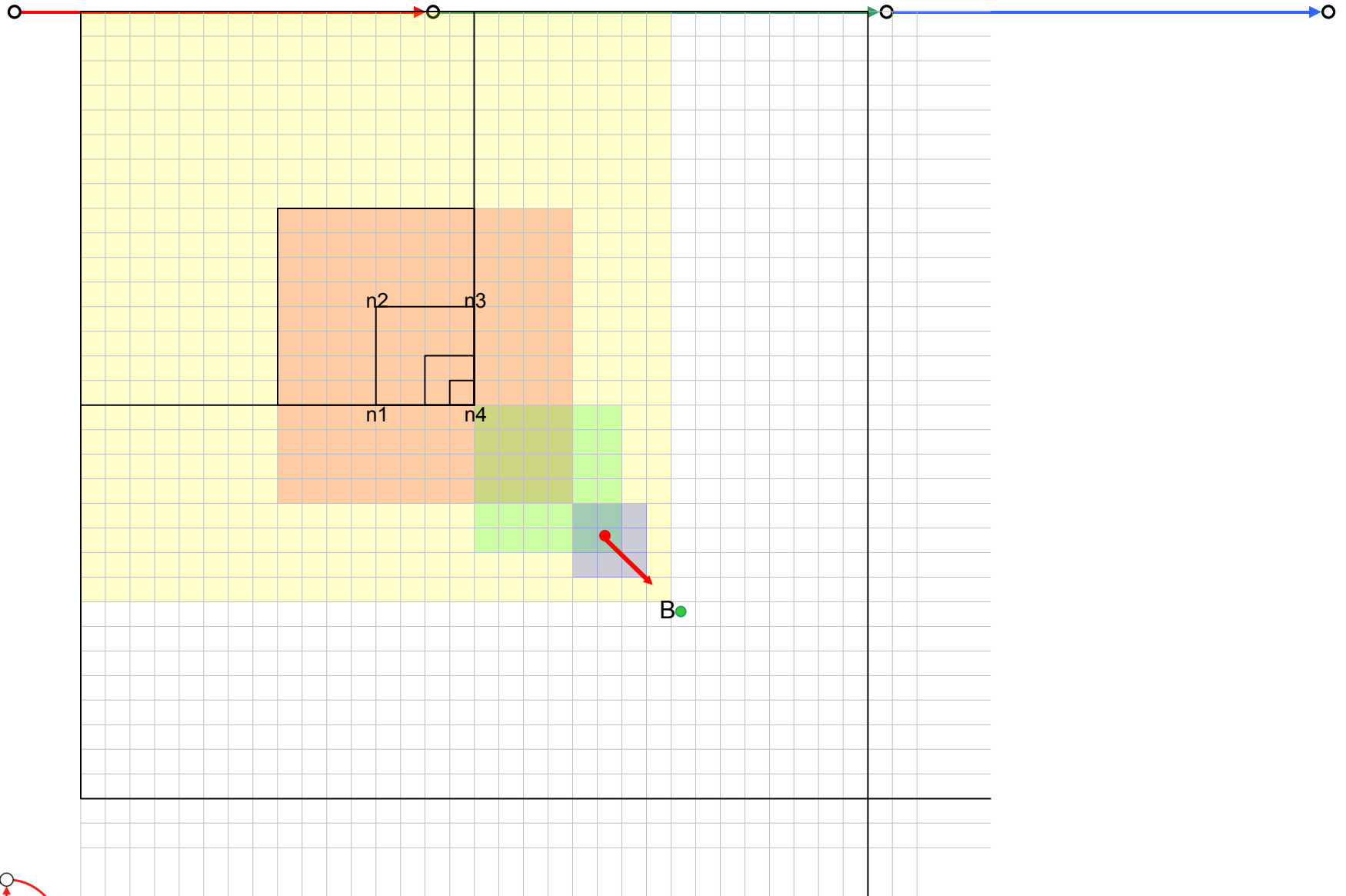




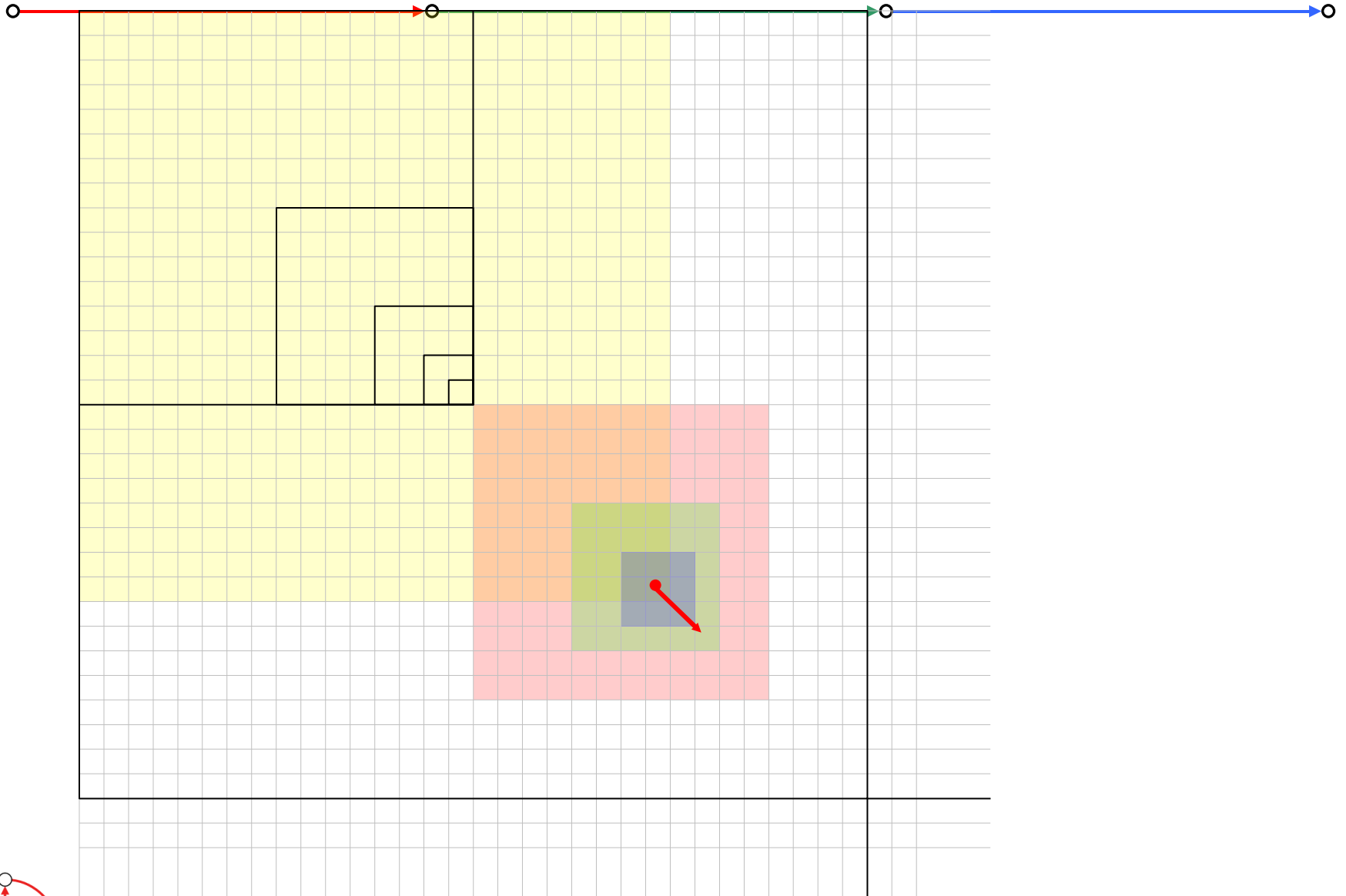
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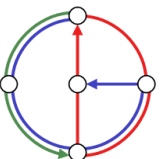
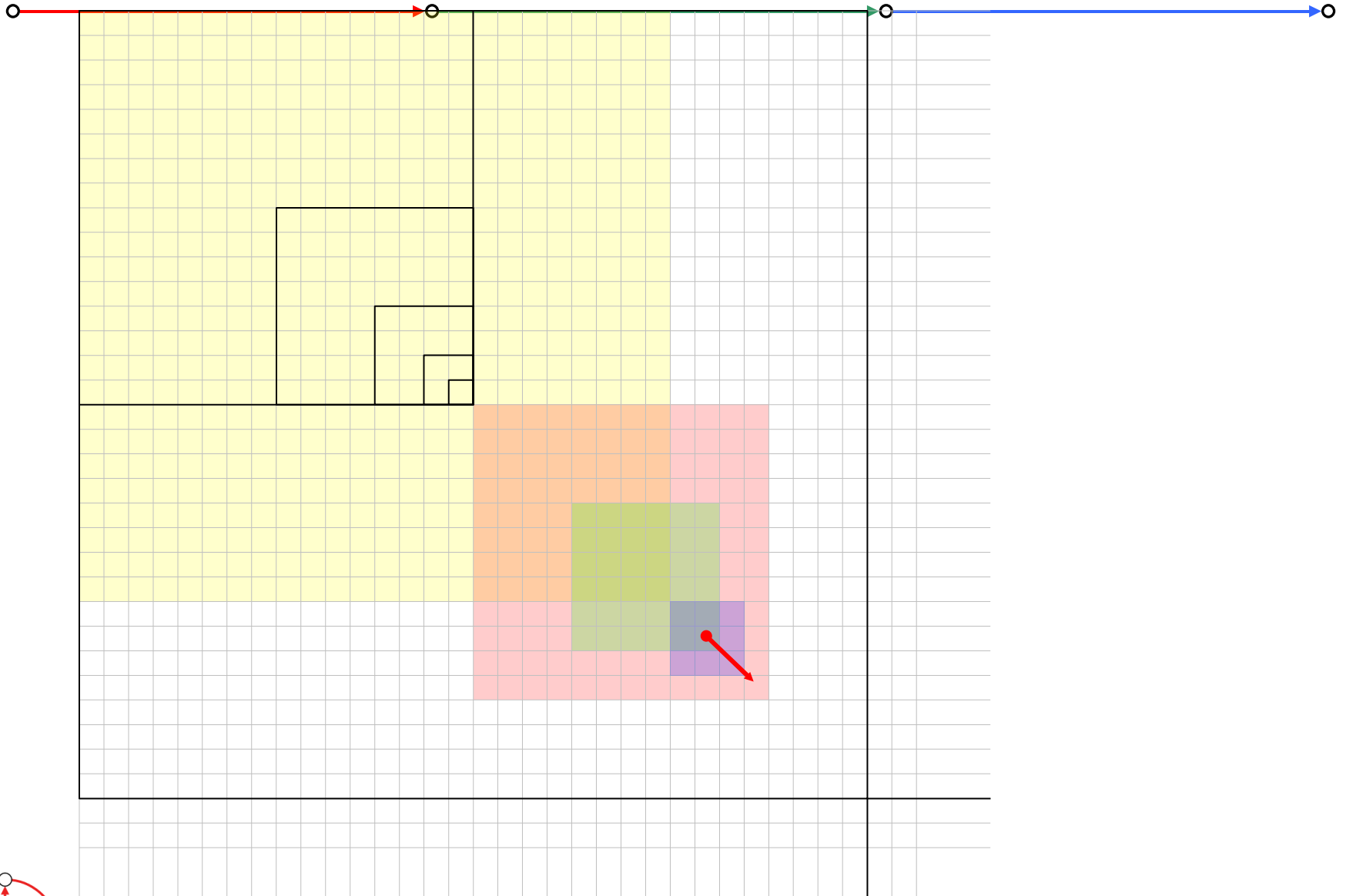
# LLS Worst Case



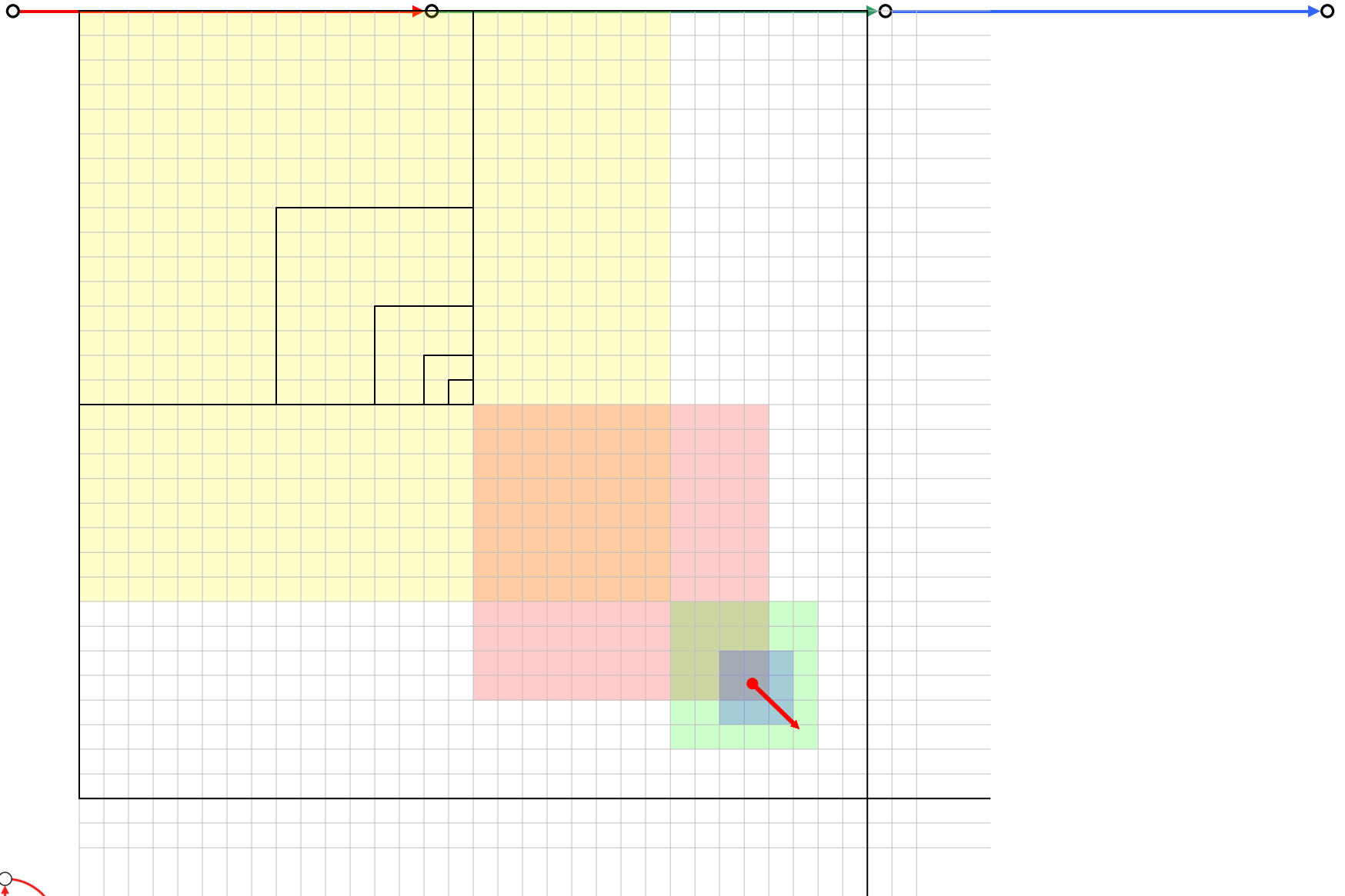
# LLS Worst Case



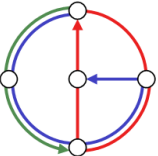
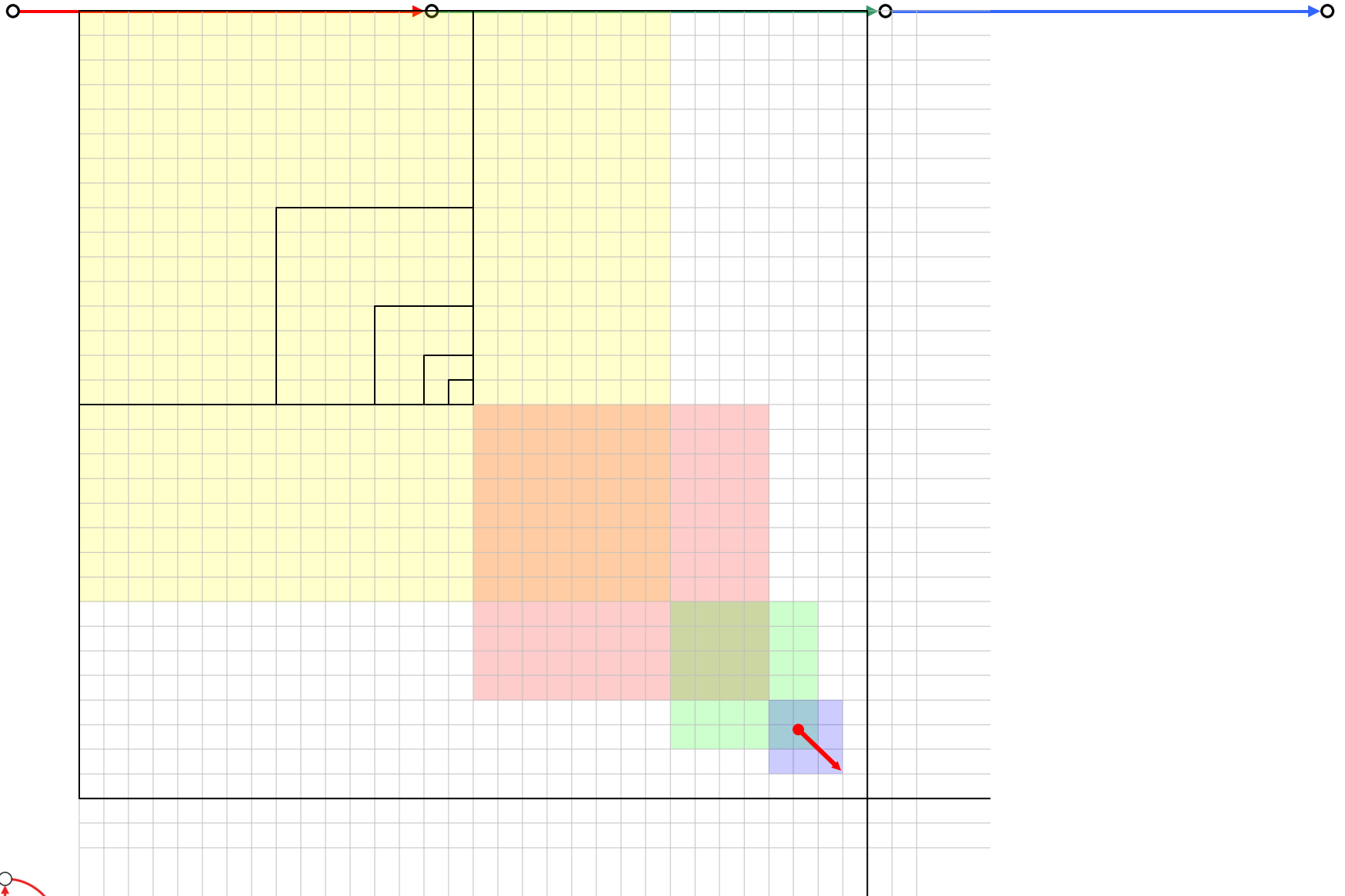
# LLS Worst Case



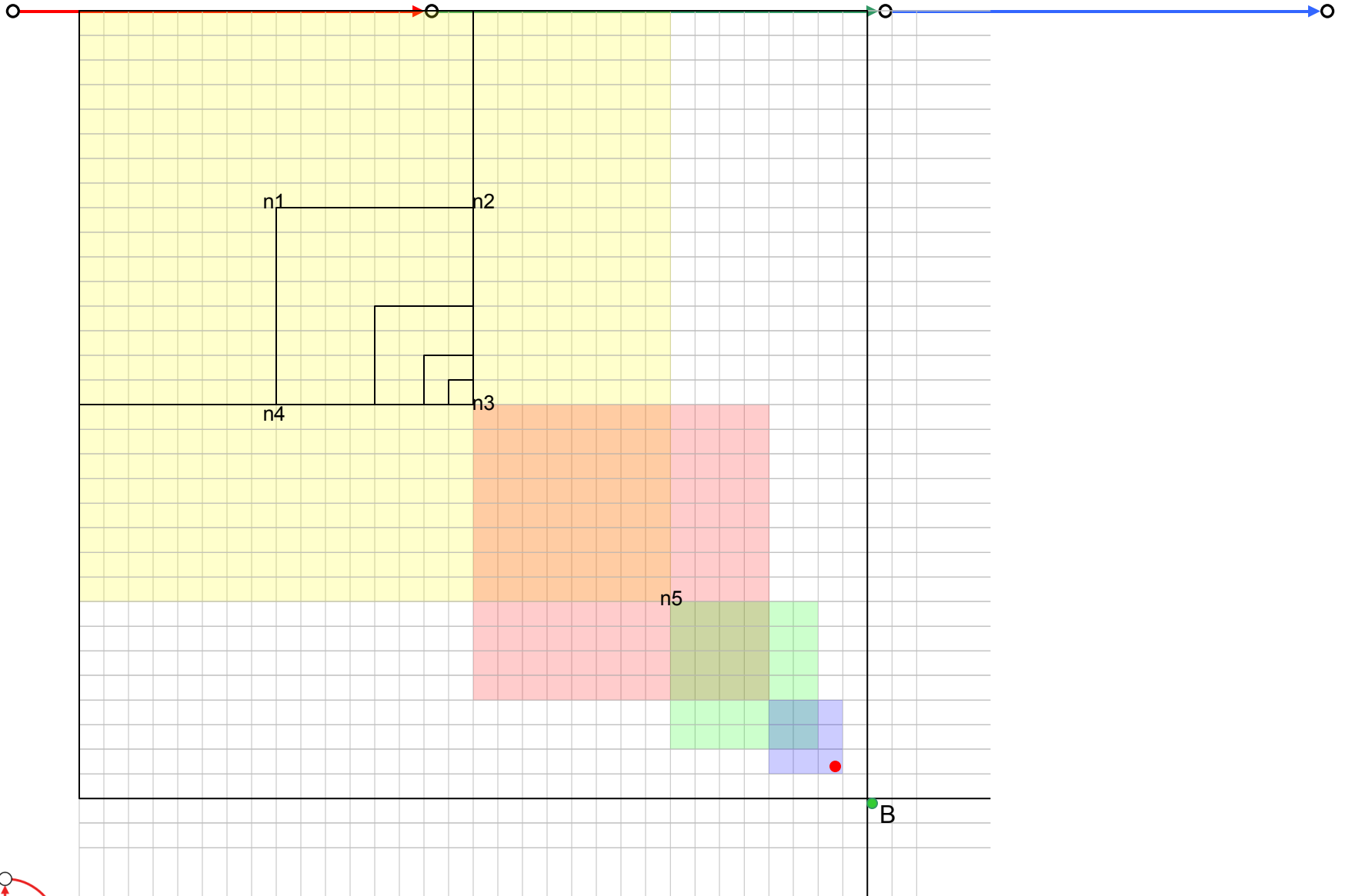
# LLS Worst Case



# LLS Worst Case



# LLS Worst Case



# LLS Worst Case

